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#### 20. ABSTRACT (Continue on reverse side if necessary and identify by block number)

A first-order mathematical model of the frequency measuring portion of the Bragg-Cell radar receiver is developed in this report. This model is implemented in a computer program (listed in the appendix) Various combinations of assumed uniform and Gaussian distributions for the IF and acoustic signals are input to obtain a graphical frequency output from the model. Comparison with actual Bragg-Cell output is not attempted.

#### U.S. ARMY INTELLIGENCE CENTER AND SCHOOL Software Analysis and Management System

BRAGG-CELL RECEIVER STUDY

**EAAF** 

Technical Memorandum No. 19

10 April 1987

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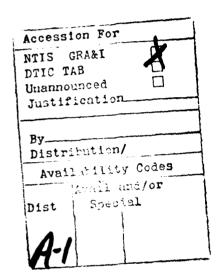
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#### **PREFACE**

The work described in this publication was sponsored by the United States Army Intelligence Center and School. The writing and publication of this paper was supported by the Jet Propulsion Laboratory, California Institute of Technology, under a contract with the National Aeronautics and Space Administration, NAS 7-918, RE 182, A187.





#### EXECUTIVE SUMMARY

This Technical Memorandum was prepared originally as part of the Generic ELINT/COMINT Sensor Report (FY-86) which was elminimated under the FY-87 statement of work (SOW #2), undated (delivered to JPL 19 November 1986).

The purpose of the Generic ELINT/COMINT Sensor Report, of which this paper was intended (in its final form) to become part of, was to establish a basic superhetrodyne receiver based sensor model and perform simulations with it to determine the shaping or coloring of the statistical distributions of the radar free-space signal parametrics by a typical sensor prior to reaching the self-correlation processes. It was also intended for incorporation into the algorithm test bed so algorithms could be tested with realistic distorted data rather than unrealistic stastically pure data.

This work was originated in support of unanswered questions from previous self-correlation studies. The modeling and simulation approach was used because "live date" could not be obtained.

This paper is being published because it was completed in FY-86 with FY-86 funds and still serves a useful function.

Several significant results were noted while performing simulations on this model. The first order math model is developed for the Bragg-cell receiver. Whether the input distributions were uniform or Gaussian, the output distributions were found to be shaped so as to append a staircased triangular distribution.

## SigPro Systems

BRAGG-CELL RECEIVER STUDY

FINAL REPORT

**MARCH 1987** 

JPL CONTRACT No. 957474 Mod. No. 1

This work was performed for the Jet Propulsion Laboratory, California Institute of Technology, sponsored by the National Aeronautics and Space Administration.

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#### **ABSTRACT**

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Bragg-cell receivers are employed in specialized Electronic Warfare (EW) applications for the measurement of frequency. Bragg-cell receiver characteristics are fully characterized for simple RF emitter conditions, but less understood for complex and wideband RF emitter signals. This receiver is early in its development cycle when compared to the IFM receiver.

Functional mathematical models are derived and presented in this report for the Bragg-cell receiver. Theoretical analysis is presented and digital computer signal processing results are presented for the Bragg-cell receiver. Probability density function analysis are performed for output frequency.

Probability density function distributions are observed to depart from assumed distributions for wideband and complex RF signals. This analysis is significant for high resolution and fine grain EW Bragg-cell receiver systems.

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#### NEW TECHNOLOGY

None

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#### INTRODUCTION

The development effort is for theoretical analysis, software algorithms implementations, signal processing analysis, and test analysis for probability density function characterization of a Bragg-cell receiver system. SigPro Systems Inc. is performing this work under JPL Contract No. 957474, Mod. No. 1.

This final report describes the completed study on the Bragg-cell receiver. A functional mathematical model is derived for the receiver. This math model is implemented into digital computer software and signal processing analyses are performed.

Theoretical analysis is developed for the Bragg-cell receiver. Ideal and practical subsystem implementations are presented and analyzed. The key ELINT parameter of interest is frequency, hence, the theoretical analysis presents the basic analysis approach for frequency. Probability density function analysis is presented for first-order subsystem model.

The theoretical model for the Bragg-cell is developed into a digital computer program. All computer programs are listed in Appendix A.

Signal processing analysis is performed using the derived first-order model. The pdf characteristics of the Bragg-cell receiver's output frequency are determined for assumed input frequency pdf (constant and Gaussian) characteristics.

X

#### BRAGG CELL RECEIVER

#### INTRODUCTION

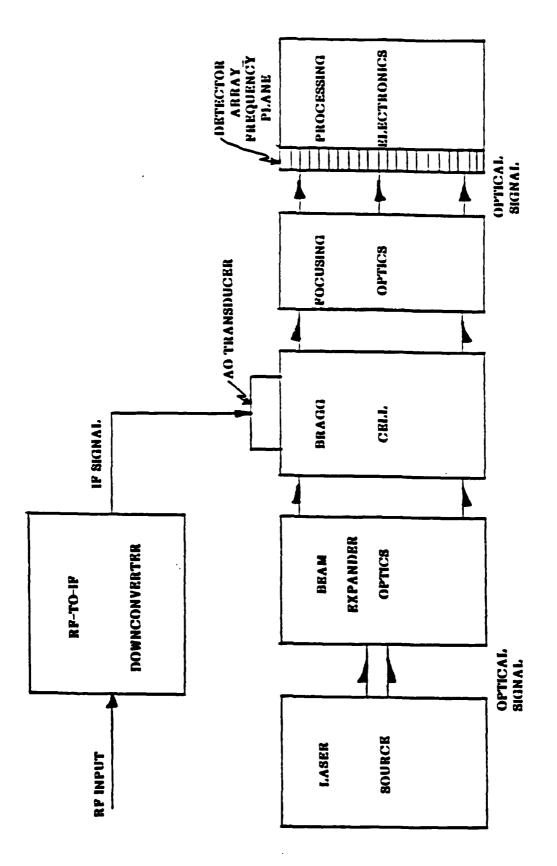
A Bragg-cell receiver is used to measure frequencies of input RF radar pulses, with wide frequency coverage, large dynamic ranges and simultaneous or time coincident signals. The ideal Bragg-cell receiver will measure the frequency parameter on a single pulse basis with no distortion. Practical Bragg-cell receivers will distort the frequency characteristic of a radar emitter because the ideal Bragg-cell receiver characteristics are difficult to approximate in real life.

The radar's frequency parameter can be characterized using a random variable. The random variable may be quantified by the probability density function (pdf), mean value, variance and other moments. As a radar signal passes through the Bragg-cell receiver the random signal description is modified or distorted by the receiver's nonlinear transfer function characteristic. Bragg-cell receiver characterization of RF frequency will differ from actual rs. \_ emitter characterization by multifaceted distortion effects.

This section presents a functional description of the Bragg-cell receiver with potential distortion sources and mechanisms and a first-order Bragg-cell receiver model is developed. This Bragg-cell receiver model is used to analyze the distortion of the frequency's pdf. The first-order Bragg-cell receiver model is limited to key distortion effects.

#### IDEAL BRAGG-CELL RECEIVER CHARACTERIZATION

A functional block diagram of a Bragg-cell receiver is shown in Figure 1. The basic receiver includes an RF-to-IF downconverter, Bragg-cell with AO transducer, laser source, beam expander optics, beam focusing optics, detector array and processing electronics.



PICIURE 1. Punctional Block Diagram of a Bragg-Cell Receiver.

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The RF input signal is characterized by

$$\chi(t) = \chi(t) \cos[\omega_{et} + \phi(t)]$$
 Eq. 1

where

x(t) = Pulsed or CW signal,

X(t)= amplitude modulation function.

We = fixed angular carrier frequency,

 $\phi(t)$  = phase deviation function.

The RF-to-IF downconverter is described in Reference 1. The ideal downconverter is composed of an ideal local oscillator which is a perfect CW signal, a perfect product mixer, and an ideal bandpass filter. The ideal IF signal output from the downconverter is described quantitatively by:

$$y(t) = X(t) \cos \left[ \omega_{xx} t + \phi(t) \right]$$
 Eq. 2

Equation 2 is identical to Equation 1 with the fixed angular frequency being changed from  $\mathbf{w}_{\mathbf{C}}$  to  $\mathbf{w}_{\mathbf{IP}}$ . The IF center frequency is chosen to match the center frequency of the Bragg-cell and AO transducer. Ideally the IF signal replicates the input RF signal. The RF-to-IF downconverter is described and characterized in Reference 1. RF-to-IF downconverter analysis will not be presented in this report.

The IF signal drives the AO transducer which launches an acoustic signal through the Bragg-cell. Specifically, the IF electronic signal is converted into an acoustic wave (slow wave replication of the IF signal) which propagates

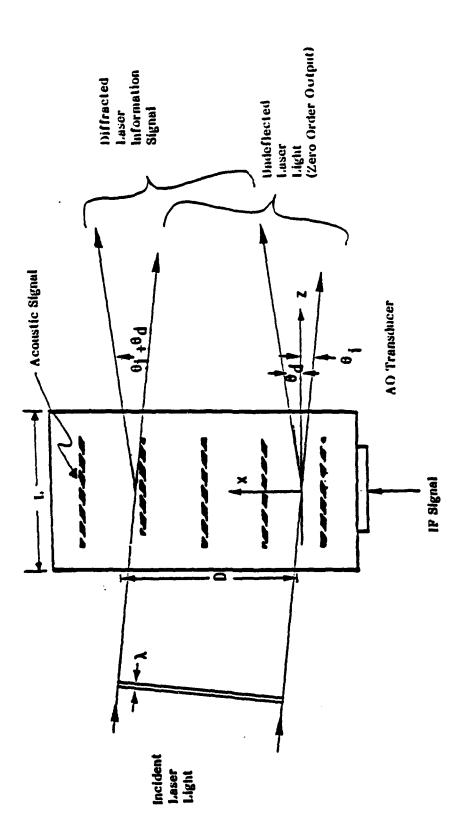
through the optically transparent Bragg-cell. Through the elasto-optic effect. the acoustic wave produces a spatial modulation of the refractive index in the Bragg-cell (Reference 2.)

The laser source is expanded by the beam expander optics and illuminates the Bragg-cell. As the laser light passes through the Bragg-cell, the refractive index variations produced by the acoustics wave (which is a slow form replica of the IF signal) are impressed onto the optical signal as a spatial phase modulation.

Focusing optics are used to equivalently Fourier transform the modulated optical beam. Resultant optical Fourier transform signal is focused onto the detector array or frequency focal plane (see Figure 1.) The photodiode detector array is used to capture and convert the optical signal to an electronic signal representation. The detector array is a linear photodiode array which is functionally used to detect and measure light intensity versus frequency of the transformed optical signal. The detector array is electronically read by the processing electronics, which also provides follow-on signal processing functions.

The Bragg-cell modulator is depicted in Figure 2. The incident laser light interacts with the acoustic signal in the cell to produce a diffracted light information signal along with undeflected laser light signal. The diffracted laser signal is also frequency shifted by the acoustic signal frequency. The incident laser light hits the Bragg-cell at an angle  $\theta_{\rm t}$  with respect to the z axis. The IF electronic signal is sent to the AO transducer to convert the IF signal to a replica acoustic signal. The acoustic wave of frequency  $f_{\rm q}$  propagates with velocity  $v_{\rm m}$  along the  $x_{\rm m}$ -axis in the Bragg-cell.

The diffracted laser light signal results from the AO interaction effects between the incident laser beam and the acoustic information bearing signal



Pigure 2. Bragg-Cell Modulator

in the Bragg-cell. Maximum diffracted laser light energy occurs in the first order beam when (Reference 2):

$$\Theta_i = \sin^{-1}\left[\frac{\lambda f_i}{2 V_s}\right]$$
 Eq. 3.

and

$$\Theta_{d} = \Theta_{i}$$

where

2 = Wavelength of laser light

 $\mathcal{L}$  = Frequency of acoustic wave

 $V_S$  = Velocity of acoustic wave in Bragg-cell along the x-axis.

 $\Theta$ ; = Effective angle of incident laser light.

e Effective angle of first order diffracted laser light information signal.

Detailed Bragg-cell analysis would require AO cell refractive index variations analysis for precise quantification. This first order Bragg-cell model does not require this detailed analysis. Functionally the Bragg-cell model is accurate and conceptually clear for the external angles  $\theta$  i and  $\theta$ <sub>d</sub>.

Bragg-cell processors are, in general, configured so that  $\theta_i << 0.1$  radian, hence, Equation 3 can be readily and accurately simplified to:

$$\Theta_i = \frac{\lambda f_i}{2 V_3}$$
. Eq. 5.

Using Equation 4 and 5, the following equation for the effective angle of the first order diffracted laser light information signal is:

$$\Theta_{d} = \frac{\lambda f_{1}}{2 V_{5}}$$
 Eq. 6

Equation 6 reveals that  $\theta_{\underline{d}}$  varies directly with the acoustic wave frequency. As stated earlier, the IF signal frequency is related to the acoustic wave frequency by: (Reference 2)

$$f_{xx} = K f_1$$
Eq. 7.

where K is a constant.

Equation 8 results by combining Equations 6 and 7,

$$\Theta_d = \frac{2 + V_S}{2 + V_S}$$

Equation 8 shows that 9, varies directly with the IF signal carrier frequency.

The actual displacement of the diffracted laser information signal from the undeflected laser light (see Figure 2) is given by (Reference 2.)

$$d = \frac{F \lambda f_{IF}}{K V_S}$$
 Eq. 9.

where F is the focal length of the focusing optics.

A fixed Bragg-cell receiver will result in Equation 9 reducing to:

$$d = K_1 + F_{IF}$$
 Eq. 10

The actual displacement, d, of the diffracted laser beam relative to the undeflected laser light passing through the Bragg-cell is directly proportional to the IF frequency of the input IF electronic signal. The diffracted laser beam will hit the linear detector array at a specific location which corresponds to one IF frequency. The Bragg-cell receiver is calibrated by varying the IF frequency of the input IF signal over the entire operating bandwidth and capturing and analyzing the electrical output signal from the linear detector array. Detector array element signal versus IF frequency characteristic is used to quantify the Bragg-cell receiver's frequency measurement performance.

The undeflected laser light is (the zero-order output from the Bragg-ceil) described by:

$$Q_{o}(t) = L_{o}(t) \cos \left[ 2\pi f_{s} t + \Upsilon(t) \right]$$
 Eq. 11.

where

as:

Q<sub>e</sub>(t) = undeflected laser light signal.

L\_(t) = amplitude or intensity of undeflected laser light signal.

f. = laser light frequency

Υ(t) = phase variations on laser light signal.

The diffracted laser information signal is quantified mathematically

$$Q_{1}(t) = L_{1}(t) \cos \left[2\pi (f_{0} + f_{1})t + \delta(t)\right]$$
 Eq. 12.

where

 $Q_1(t) = Diffracted laser information signal.$ 

L<sub>1</sub>(t) = Amplitude or intensity of diffracted laser information signal.

 $\frac{C_2}{C_2} + \frac{C_3}{C_3} =$  Frequency of information signal.

S(t) = Phase variations of information signal.

Equation 12 reveals that the diffracted laser output signal is frequency shifted. The frequency shift is produced by the laser light signal and acoustic signal interaction in the Bragg-cell.

The Bragg-cell receiver is conceptually a parallel, multi-channel spectrum analyzer, which determines the Fourier magnitude spectrum of the input IF signal. The electronic circuit model for the Bragg-cell receiver is depicted in Figure 3. The IF signal input is applied to a parallel narrowband filter bank with an associated diode detector and filter bank. Each output signal is a power or energy indicator of the IF signal spectral content in each selected narrowband filter.

#### PRACTICAL BRAGG-CELL RECEIVERS

The ideal Bragg-ceil receiver is characterized in the previous section, with the measured frequency being derived from Equations 9, 10, and 12. This section will identify and briefly present some key differences between practical Bragg-ceil receivers and the ideal bragg-ceil receiver. The Bragg-ceil receiver, shown in Figure 1, is a reference for this discussion.

ELECTRONIC DETECTOR

ELECTRONIC BRAGG-CELL

#### BRAGG CELL

The ideal Bragg-cell is assumed to have an undistorted acoustic signal replica (at acoustic frequency) of the IF input signal propagating through the cell. The AO transducer provides this electronic IF signal to acoustic signal conversion. The AO transducer has transfer function nonlinearities, which produces unwanted and added acoustic signal components. Simple sinusoidal electronic signals are subject to minor variations, while complex and wideband signals may be significantly distorted by the nonlinear transducer action.

The ideal Bragg-cell is assumed to provide a perfect acoustic signal termination, at the far end of the cell. In general, the acoustic signal termination is not perfect, which cause low level acoustic signal reflections and distortion generated signal components to propagate back through the cell. These reflected acoustic signals are considered as additional distortion sources, hence, variations in the diffracted laser information signal can be expected.

Actual distortion effects are determined by AO transducer nonlinearities, reflected acoustic signal levels, total acoustic signal parameter descriptors and Bragg-cell properties. The complete acoustic signal's instantaneous frequency is determined by amplitudes, frequencies, and phases of desired acoustic signal, undesired reflected acoustic signals and nonlinearly generated and unwanted acoustic signals. Frequency variations produced by instantaneous frequency changes will produce angle variations in the diffracted laser information signal; thus, frequency measurement errors in the Bragg-cell receiver.

#### LASER SOURCE

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The laser light source is ideally assumed to be constant amplitude and fixed frequency signal. Actual laser sources can have some minor frequency shifts. Minor frequency shifts will results in small angle variations in the diffracted laser information signal. (See Equation 3.)

Frequency variations will widen the effective spotsize and change the angle of the diffracted laser beam, which means the light energy may be spread over more detector elements in the linear detector array.

The laser light signal does not have a constant intensity or amplitude. The amplitude is quantified by deterministic and random signal components. These amplitude variations will result in diffracted laser information signal intensity level variations at the detector plane.

#### OPTICS

Beam expander optics and diffraction signal focusing optics are fundamental modules in the Bragg-cell receiver. Beam expander optics shape the coherent laser beam to illuminate one entire side of the Bragg-cell. This beam expansion provides a long path interaction between the acoustic signal and laser light within the Bragg-cell. Beam expander optics and laser source are positioned so that the laser light strikes the cell at the Bragg angle. Nonlinearities, positional variations, and rotational variations in the beam expander optics can produce amplitude and angle variations in the diffracted laser information signal. These errors are usually very small for well-designed optics.

Focusing optics are used as the so-called Fourier transform lens. The Bragg-cell is positioned in the front focal plane of the lens. The photodetector

array is positioned at the back focal plane of the lense. (Reference 3.) Again, nonlinearities and location variations in the focusing optics variations can produce intensity and angle variations in the diffracted laser information signal. These errors are also very small in well-designed optics.

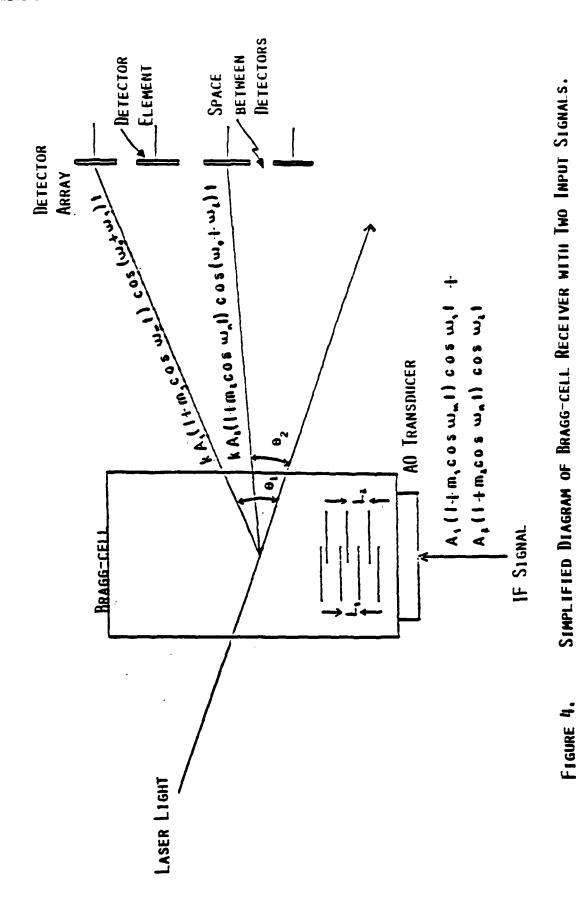
#### DETECTOR ARRAY

The ideal detector array is assumed to be a long linear array with high frequency resolution and sensitivity. Practical Bragg-cell receivers use long linear photodiode arrays, where typically 512 or 1024 photodiodes are closely spaced along the array length.

Figure 4 presents an illustration of two diffracted laser information signals striking the photodetector array at two different diodes (two different frequencies.) In actual practice, the light spotsize for each beam is larger than the area of one photodiode; hence, the light spills onto the area between detectors and also onto adjacent detectors.

Diffracted laser information signal angle variations (frequency variations) produce energy spread over several or many photodiode cells. Each photodiode cell is used to determine the signal energy in resolved and calibrated frequency space. The photodetector array is electronically readout to determine frequency and amplitude information for each diffracted laser light information signal. The photodetector array is functionally and practically described as a frequency sampling unit, with 512 to 1024 frequency bins. Each photodiode determines the elemental frequency resolution.

Bragg-cell receivers can accurately measure frequencies of time coincident or time overlapped signals, which is a big advantage over other receivers, such as the IFM receiver. These receivers are available with bandwidths to approximately 1 GHz, and frequency resolutions of 100 KHz to 10 MHz. The



**7** 33 8 \* 888 B B 339 M 7 FIGURE 4. 3 

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Bragg-cell receiver's dynamic range is approximately 30 to 40 db. with the photodetector array's dynamic range being the critical limiting factor.

### PROBABILITY DENSITY FUNCTION ANALYSIS BRAGG-CELL RECEIVER

The probability density function (pdf) of the Bragg-cell receiver's measured frequency parameter is considered in this section. The pdf characteristic is developed for a first order Bragg-cell receiver model under high signal-to-noise ratio conditions. The IF signal's frequency characteristic is assumed to have a constant pdf or a Gaussian pdf.

Ideal and practical Bragg-cell receivers are discussed earlier in this report, and characteristics equations are provided for the ideal receiver. The Bragg-cell and AO transducer are key producers of first-order distortion effects. Distortion effects include AO transducer nonlinearities and reflected acoustic signals returning from the far end of the Bragg-cell. This analysis assumed that acoustic signals generated by AO transducer nonlinearities are significantly larger than reflected acoustic signals.

The ideal Bragg-cell receiver contains a single acoustic signal

$$3(t) = Z(t) \cos[2\pi f_1 t + d_1(t)]$$
 Eq. 12

which results in the diffracted laser information signal given in Equation 12.  $f_1$  is the frequency of the acoustic signal, which is directly related to the frequency of the input IF signal. (See Equation 7.)

AO transducer nonlinearities are producing undesired acoustic signals

in the Bragg-cell. Undesired or unwanted acoustic signals are described as a cosinusoidal series of N components (harmonics and intermodulation components at a significant energy level) which are characterized as:

$$u(t) = \sum_{m=3}^{N} U_m(t) \cos \left[ 2\pi f_m t + d_m(t) \right]$$
 Eq. 14.

where

U(t)= Total unwanted acoustic signals in Bragg-cell. The AO transducer will generate harmonics of f<sub>1</sub> and other intermodulation frequency components.

Un(t) = Amplitude of n th. unwanted acoustic signal component.

 $\frac{C}{T_m}$  = Frequency of n th. unwanted acoustic signal component.

Harmonics of  $f_1$  and intermodulation frequency components are present.

 $G_m(t)$  = Phase variations of n th. unwanted acoustic signal component. The total acoustic signal in the Bragg-cell is found by summing Equations 13 and 14:

$$w(t) = 3(t) + u(t)$$

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Equation 15 can be rewritten, with a lot of work, as:

$$w(t) = Z(t) A(t) \cos \left[ 2\pi f_1 t + d_1(t) + \beta(t) \right]$$
 Eq. 16.

$$A(t) = \sqrt{\left[\sum_{n=2}^{N} S_n(t)\right]^2 + \left[1 + \sum_{n=2}^{N} C_n(t)\right]^2}$$

$$\beta(t) = tan^{-1} \frac{\sum_{m=2}^{N} S_m(t)}{1 + \sum_{m=2}^{N} C_m(t)}$$

$$S_{m}(t) = K_{m} SIN \left( 2\pi \Delta f_{m} t + \Delta \Theta_{m} \right)$$

$$C_{n}(t) = K_{m} Cos \left( 2\pi \Delta f_{m} t + \Delta \Theta_{m} \right)$$

$$K_{m} = \frac{U_{m}(t)}{Z(t)}$$

$$\Delta f_{m} = f_{m} - f_{m}$$

$$\Delta\Theta_{m}=d_{m}(t)-d_{1}(t)$$

The instantaneous frequency variation, resulting from  $\beta(t)$  phase variations in Equation 16, is

$$\Delta f_{i}(t) = \frac{\left[\sum_{m=2}^{N} S_{m}(t)\right] \left[\sum_{m=2}^{N} \Delta \omega_{m} S_{m}(t)\right] + \left[1 + \sum_{m=2}^{N} C_{m}(t)\right] \left[\sum_{m=2}^{N} \Delta \omega_{m} C_{m}(t)\right]}{2 \text{ TT } A^{2}(t)}$$
Eq. 17.

The instantaneous frequency variation is a very complex function of amplitudes, frequencies, and phases of all unwanted acoustic signal components in the Bragg-cell. Equation 17 can be rewritten using the Fourier series expansion as a fixed frequency plus a series of harmonically related frequency components. A first-order approximation is the reduction of Equation 17 to a fixed frequency,

$$\Delta f_i(t) \doteq f_z$$
 Eq. 18.

 ${\bf f_2}$  is used to approximate the resultant frequency component, which is produced by unwanted acoustic signal components propagating in the Bragg-cell.

Resultant phase variations are approximated as:

$$\beta(t) \doteq 2\pi f_2 t$$

The total acoustic signal (Eq. 16) can be approximated as:

$$u(t) \doteq Z(t) A(t) \cos \left[ 2\pi f_1 t + 2\pi f_2 t + \alpha_1(t) \right]$$
 Eq. 20.

The total instantaneous frequency of w(t) (Equation 20) is:

$$f_i(t) \doteq f_i + f_2$$
 Eq. 21.

Equation 12 can be easily changed to approximate unwanted acoustic signals. The modified Equation 12 results in the following equation:

$$Q_{1}(t) = L'_{1}(t) \cos \left[2\pi (f_{2} + f_{1} + f_{2})t + \delta'(t)\right].$$
 Eq. 22.

The actual displacement of the diffracted laser information signal (Equation 22) relative to the undeflected laser light is

$$d = \frac{F \lambda (f_1 + f_2)}{V_3}.$$
 Eq. 23.

Equation 23 reveals that d is a random variable since it is a summation of two random variables  $f_1$  and  $f_2$ . Conceptually, the spot size of the diffracted laser information signal is increased by the unwanted acoustic signal components. The actual displacement d is directly calibrated to a photodiode

cell in the linear detector array, which corresponds to a specified frequency bin.

 $f_1$  and  $f_2$  are assumed to be independent random variables for this analysis. Pdf characteristics of  $f_1$  and  $f_2$  are assumed to be either constant or Gaussian. The pdf characteristic of d' is the convolution of pdf  $(f_1)$  and pdf  $(f_2)$ , if the random variables are independent (Reference 4.)

$$pdf(q_{i}) = \int_{\infty}^{\infty} bqt(q_{i} - t_{i}) bqt(t_{i}) qt_{i}$$
Eq. 24.

where

$$d' = d \frac{V_s}{F\lambda}$$
.

Each frequency bin in the linear photodiode array exactly corresponds to Ad bin coverage in displacement space.

The output frequency of the detector array is

$$f_0 = K_2 d$$
 Eq. 25.

Substituting Equation 25 into Equation 23, the result is:

$$f_0 = \frac{K_2 F \lambda (f_1 + f_2)}{V_3}.$$
Eq. 26.

The Bragg-cell receiver's measured output frequency can be stated in terms of the input IF signal's frequency by using Equations 26 and a modified version of Equation 7. The output frequency is:

$$f_{D} = K_{3} (f_{IF} + f_{2}^{4})$$
 Eq. 27.

where

$$K_3 = \frac{K_2 F \lambda}{K V_S}$$

 $f_D$  is a linear combination of two random variables  $f_{IF}$  and  $f_{IF}^4$ , which are assumed to be independent. The pdf  $(f_D)$  is the convolution of pdf  $(f_{IF})$  and pdf  $(f_D^4)$ , which is expressed mathematically as:

$$pdf(f_0) = \int pdf(f_0 - f_{IF}) pdf(f_{IF}) df_{IF}$$
. Eq. 28.

The pdf  $(f_D)$  characteristic is functionally divided into sampled  $\Delta f_D$  bins by the photodiode cells in the linear detector array. This frequency domain binning process is equivalent to discrete sampling of the pdf  $(f_D)$ 

characteristics in  $\Delta f_D$  bin widths.  $\Delta f_D$  is the basic frequency resolution of the Bragg-cell receiver at the linear detector array. The actual pdf characteristic of the Bragg-cell receiver's frequency parameter is a discrete characteristic, which is a function of the pdf of the IF signal frequency and pdf characteristic of the equivalent unwanted signal components.

#### SIGNAL PROCESSING ANALYSIS

#### INTRODUCTION

Signal processing analysis results are presented in this section. The Bragg-cell receiver model is implemented on a Hewlett Packard Integral computer. Computer software program listings are contained in Appendix A of this report.

Pdf analysis of the Bragg-cell receiver's frequency parameter is performed, assuming constant and Gaussian pdf characteristics for the input signal's IF frequency. Pdf analysis is performed for selected frequency resolutions of the Bragg-cell receiver. Also, statistical analysis are performed on output pdf signals and summary results are presented.

#### BRAGG-CELL RECEIVER MODEL RESULTS

The Bragg-cell receiver is math modeled in the previous section. First-order model implementation is shown to be a convolution of pdf  $(f_{IF})$  and pdf  $(f_{2}^{1})$  for the Bragg-cell receiver's output frequency pdf characteristic. Equation 28 is the final descriptive equation for the output frequency pdf characteristic.

Bragg-cell receiver signal processing results are summarized in Table 1. Signal processing analysis programs are presented in Appendix A. Figures 5 through 70 contain detailed pdf plots for the Bragg-cell receiver's output frequency parameters. These plots are made for selected pdf characteristic of  $f_{\rm IF}$  and  $f_{\rm 2}^1$  and selected Bragg-cell receiver frequency resolutions.

Table 1 defines the input signal or  $f_{IF}$  in terms of DF1 or DF1 and  $\sigma_1$ . The pdf  $(f_{IF})$  is assumed to be a constant if only a value for DF1 is given. DF1 (MHz) indicates the frequency excursion of the input frequency  $(f_{IF})$ 

For a Gaussian pdf ( $f_{\rm IF}$ ), DF1(MHz) and  $\sigma_1$ (MHz) is selected as 1.166 MHz or 4.166 MHz for Gaussian pdf's.

TABLE 1

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BRAGG-CELL RECEIVER

# SIGNAL PROCESSING RESULTS

	INPUT	SIGNAL	DISTORTIC	IN SIGNAL	DISTORTION SIGNAL FREQUENCY	0	OUTPUT FREQUENCY:	UENCY:
SOLICIES	DEI(MH1)	(4HM)	DE2(MH2)	G (MHz)	RESOLUTION	S	STATISTICAL RESULTS	(ESUL 18
1				2	(MHz)	a (MHz)	SKEW	KURTOSIS
			•			450	350 0	
<b>~</b>	₽ ;		~ (		ŗ.	400.7	0.7.0	1.307
•	2		7		• •	2.404	/67.1	\$ 67.7
7	9		7		2.0	3.103	1.010	2.165
•	0		<b>s</b> n		0.5	3.250	-0.119	2.192
•	2		v		0.1	3.422	-0.864	2.319
. 2	2		N.		2.0	4.168	1.395	2.369
-	91		Ð		0.5	3.910	0.038	2.394
2	2		•		0.1	3.922	-0.228	2.402
13	9		•		2.0	4.017	0.730	2.442
*	25		ιn		1.0	7.395	0.000	1.895
. 2	72		s		2.0	7.571	-0.581	1.967
16	25		<b>v</b> n	-	5.0	7.356	0.495	1.946
17	25		15		1.0	8.471	0.000	2.272
=	72		15		2.0	8.498	-0.155	2.281
5	52		15		5.0	8.420	-0.077	2.268
20	72		24		1.0	10.01	0.000	2.399
==	52		24		2.0	10.062	960.0	2.396
22	52		24		9.0	966.6	0.026	2.389

TABLE 1 CONT'D BRAGG-CELL RECEIVER SIGNAL PROCESSING RESULTS

	INPUT	1 1	DISTORTION	ON SIGNAL	FREQUENCY		OUTPUT FRE	FREQUENCY: CAL RESULTS
FIGURE	DFI(MHz)	q (MH2)	DF2(MHz)	o <sub>2</sub> (MHz)	(MHz)	o(MHz)	SKEW	
23	10	1.166	7		0.5	1.755	0.007	2.850
24	10	1.166	~		1.0	1.755	0.086	2.844
35	9	1.166	7		2.0	1.753	0.111	2.824
<b>7</b> 9	10	1.166	'n		0.5	2,208	900.0-	2.713
72	0	1.166	ĸ		0.1	2.209	-0.042	2.714
28	01	1.166	vn		2.0	2.207	0.023	2.704
29	72	4.166	15		1.0	6.026	-0.001	2.624
30	25	4.166	15		2.0	6.026	-0.008	2.625
31	25	4.166	15		5.0	6.022	0.009	2.617
32	22	4.166	24		1.0	8.124	0.000	2.327
33	25	4.166	24		2.0	8.124	0.003	2.327
34	<b>52</b>	4.166	24		5.0	8.122	0.000	2.324
35	91		7	0.333	0.5	2.915	0.003	1.831
36	2		~	0.333	1.0	3.257	1.174	2.192
37	10		7	0.333	2.0	2.748	0.080	1.799
38	01		'n	0.833	0.5	3.012	-0.004	1.973
39	01		15	0.833	1.0	3.102	-0.019	1.973
Q#	10		'n	0.833	2.0	3.055	0.564	2.059

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TABLE 1 CONT'D
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SIGNAL PROCESSING RESULTS

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FICTIBE	INPUT	٠. ١	DISTORTION	ON SIGNAL	A E	S	STATISTICAL RESULTS	RESULTS
		9.1		2	(MHz)	o(MHz)	SKEW	KURTOSIS
14	10		6	1.5	0.5	3.255	0.001	2.241
42	00		ø	1.5	1.0	3.255	<b>8</b> 00 <b>°</b> 0-	2.241
43	0		<b>o</b>	1.5	2.0	3.255	0.027	2.239
44	75		5.0	0.833	1.0	7.288	0.000	1.831
45	25		5.0	0.833	2.0	7.306	-0.165	1.834
46	25		9.0	0.833	5.0	6.87	1.001	1.799
47	25		15	2.5	1.0	7.653	0.00	2.037
84	25		15	2.5	2.0	7.653	-0.002	2.037
64	25		15	2.5	5.0	7.645	0.063	2.041
20	75		24	0.4	1.0	8.254	0.000	2.281
51	72		24	0.4	2.0	8.254	0.002	2.280
52	75		24	0.4	5.0	8.252	900.0	2.278
53	9	1.666	2.0	0.333	0.5	1.683	-0.003	2.842
54	2	1,666	2.0	0.333	1.0	1.683	0.076	2.842
55	9	1.666	2.0	0.333	2.0	1.680	0.039	2.804
26	01	1.666	5.0	0.833	0.5	1.845	-0.003	2.884
57	01	1.666	5.0	0.833	1.0	1.845	-0.003	2.884
58	01	1.666	5.0	0.833	2.0	1.845	0.007	2.882

TABLE 1 CONT'D BRAGG-CELL RECEIVER SIGNAL PROCESSING RESULTS

		SIGNAL		ON SIGNAL	A H	S	OUTPUT FREQUENCY: STATISTICAL RESULTS	NENCY:
FIGURE	DFILMHZ	o <sub>j</sub> (MHZ)	Dramma	0 <sup>2</sup> 1MH2)	(MIIz)	a (MHz)	SKEW	KURTOSIS
69	01	1.666	6	1.5	0.5	2.220	-0.001	2.915
9	2	1,666	o	1.5	1.0	2.220	-0.002	2.915
5	0	1.666	<b>o</b>	1.5	2.0	2.220	-0.001	2.915
62	25	4,166	'n	0.833	1.0	4.207	-0.003	2.842
63	72	•	ĸ	0.833	1.0	4.207	-0.003	2.842
3	25	•	'n	0.833	5.0	4.200	0.001	2.805
65	72	4.166	15	2.5	1.0	4.811	-0.002	2.896
99	75	4.166	15	2.5	2.0	4.811	-0.002	2.896
67	25	•	15	2.5	5.0	4.811	-0.001	2.895
5	25	4.166	24	0.4	1.0	5.719	-0.001	2.916
69	72	4.166	24	4.0	2.0	5.719	-0.001	2.916
92	25	•	24	4.0	5.0	5.719	-0.001	2.915

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The distortion signal or  $f_2^1$  is quantified in terms of DF2 or DF2 and  $\sigma_2$ . The pdf( $f_2^1$ ) is assumed to be a constant if only a value for DF2 is given. DF2(MHz) indicates the frequency excursion of the distortion signal  $f_2^1$ .

For a Gaussian pdf( $f_2^1$ ), DF2(MHz) and  $\sigma_2$ (MHz) indicates six times sigma and standard deviation, respectively. DF2 is selected as 2, 5, 9, 15, and 24 MHz.  $\sigma_2$ (MHz) is selected as 0.333, 0.833, 1.5, 2.5 and 4.0 MHz for Gaussian pdfs.

Bragg-cell receiver frequency resolution (MHz) is chosen to be 0.5, 1.0, 2.0 or 5.0 MHz. These frequency resolution selections are readily expected with current Bragg-cell receiver technology.

The last three columns of Table 1 contain statistical results of the Bragg-cell receiver's output frequency. Sigma (MHz), skew and kurtosis are computed for each output frequency pdf characteristic shown in Figure 5 through 70.

The  $pdf(f_d)$  characteristic is a staircased trapezoidal function for  $pdf(f_{IR})$  = constant and  $pdf(f_2)$  = constant. Figures 5 through 22 show numerous examples of  $pdf(f_d)$  characteristics for selected input signal and distortion signal constant pdf characteristics.  $Pdf(f_d)$  is observed to significantly depart from a constant characteristic and approach a staircased triangular characteristic as DF2 approaches DF1.

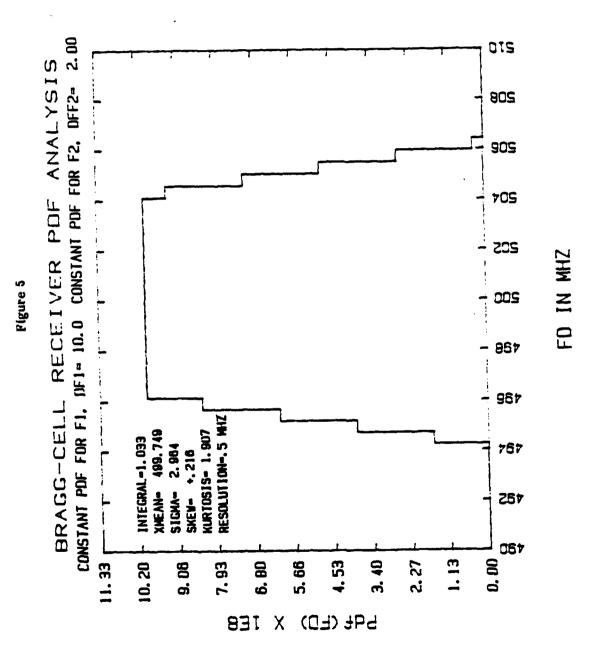
Figures 23 through 34 reveal output frequency  $pdf(f_d)$  characteristics with input frequency characteristics assumed to be Gaussian pdf and distortion signal frequency characteristics assumed to be constant pdf. These pdf characteristics are staircased Gaussian characteristics. The pdf characteristic departs from the Gaussian characteristics as the Bragg-cell receiver's frequency resolution is decreased.

Figures 23 through 34 reveal output frequency  $pdf(f_d)$  characteristics with input frequency characteristics assumed to be Gaussian pdf and distortion signal frequency characteristics assumed to be constant pdf. These pdf characteristics are staircased Gaussian characteristics. The pdf characteristic departs from the Gaussian characteristics as the Bragg-cell receiver's frequency resolution is decreased.

Figures 35 through 52 reveal output frequency  $pdf(f_d)$  characteristics with input frequency characteristics assumed to be constant pdf and distortion signal frequency characteristics assumed to be Gaussian pdf. For most example plots the long constant pdf characteristic of the input frequency tends to dominate the overall pdf characteristic. The pdf characteristics are approximately a staircased trapezoidal characteristic.

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The  $pdf(f_d)$  characteristic is a staircased Gaussian function for  $pdf(f_{IF})$  = Gaussian and  $pdf(f_2^1)$  = Gaussian. Figures 53 through 70 show numerous examples of  $pdf(f_d)$  for selected input signal and distortion signal frequency characteristics.  $pdf(f_d)$  is observed to be close to a Gaussian characteristic for all DF2 and DF1 selections. For low frequency resolution in the Bragg-cell receiver, the pdf characteristic departs from a Gaussian characteristic.



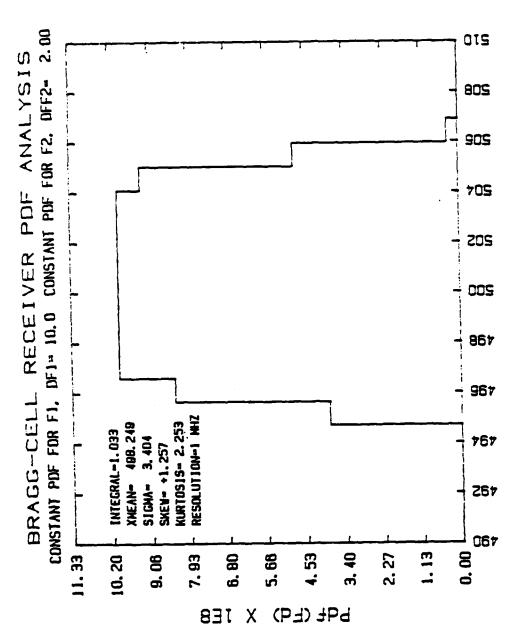
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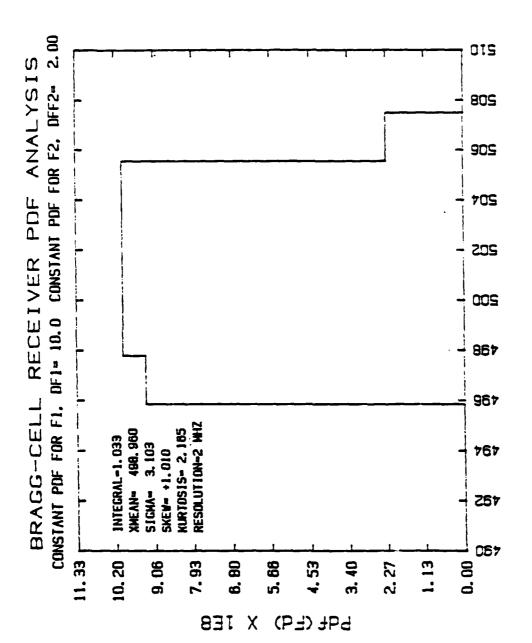
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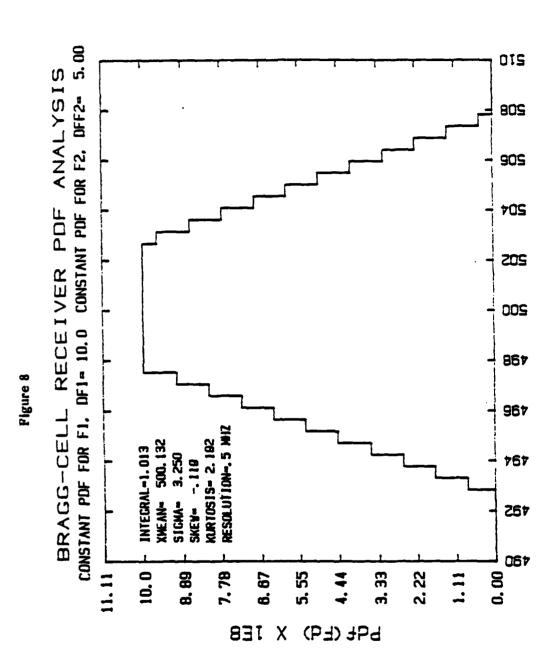
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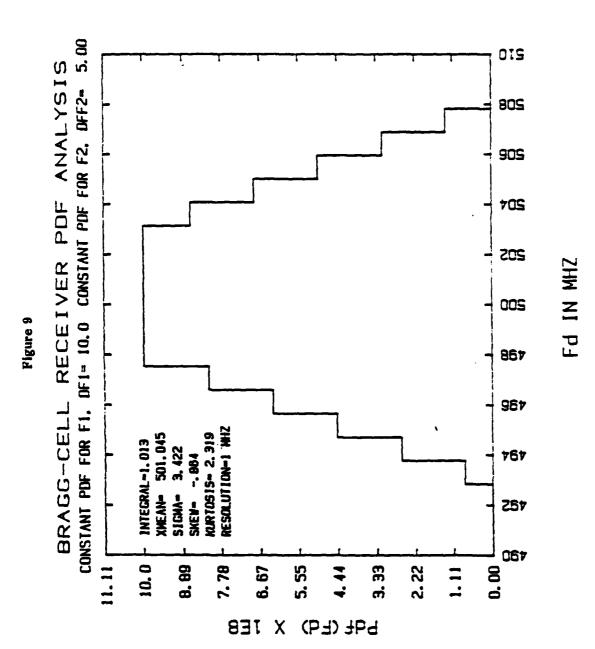
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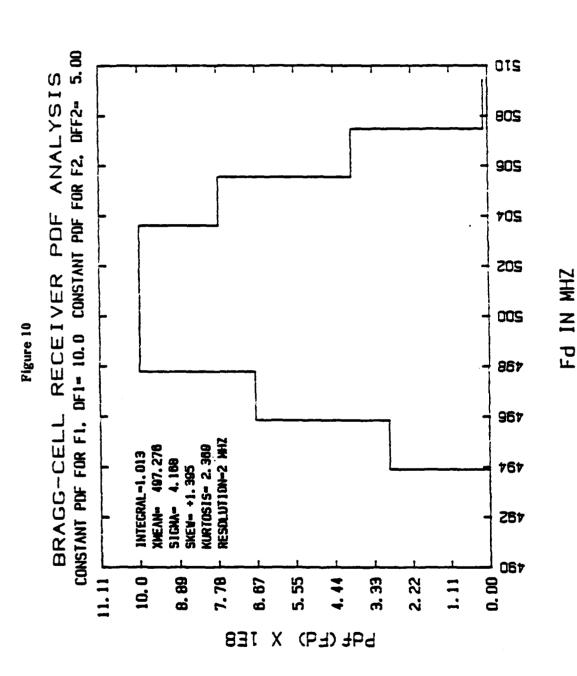
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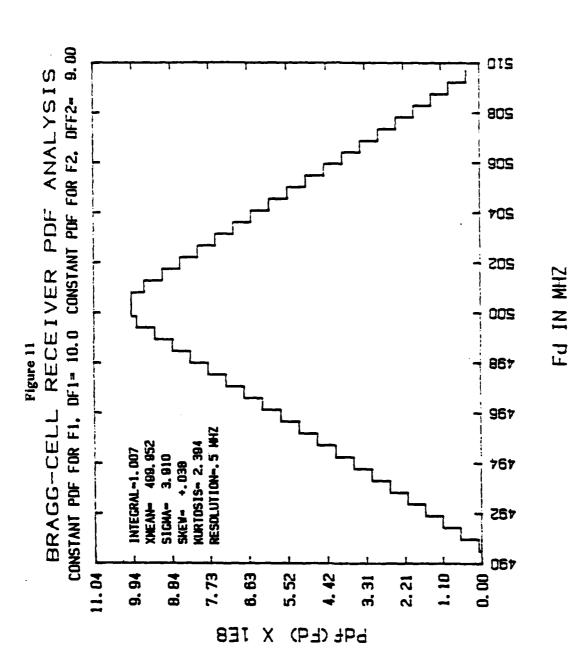
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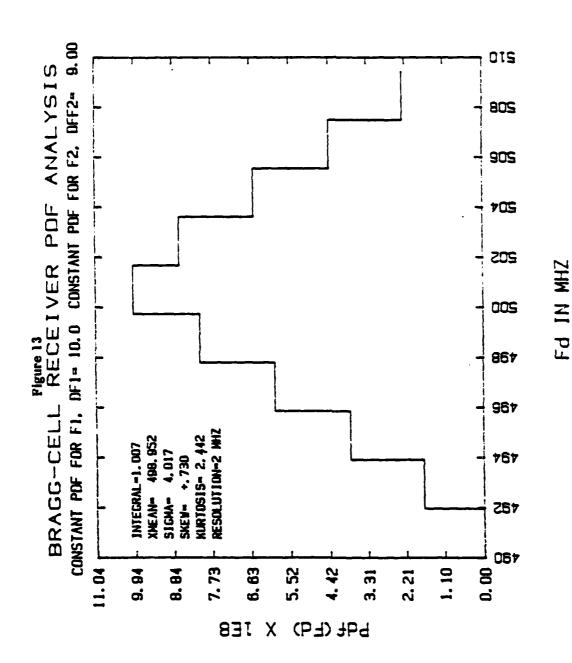
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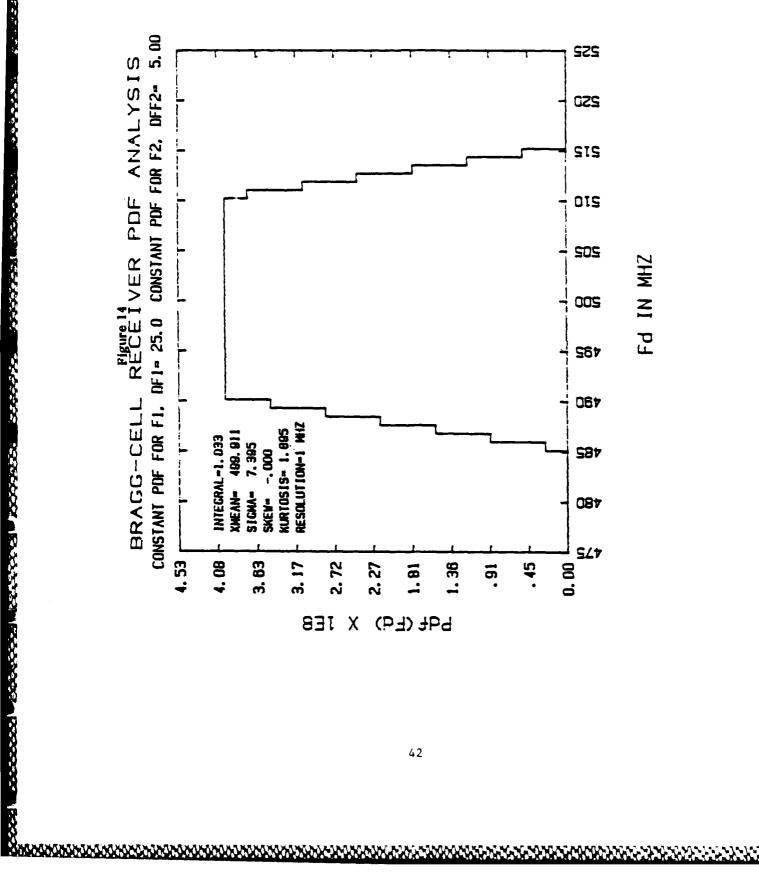
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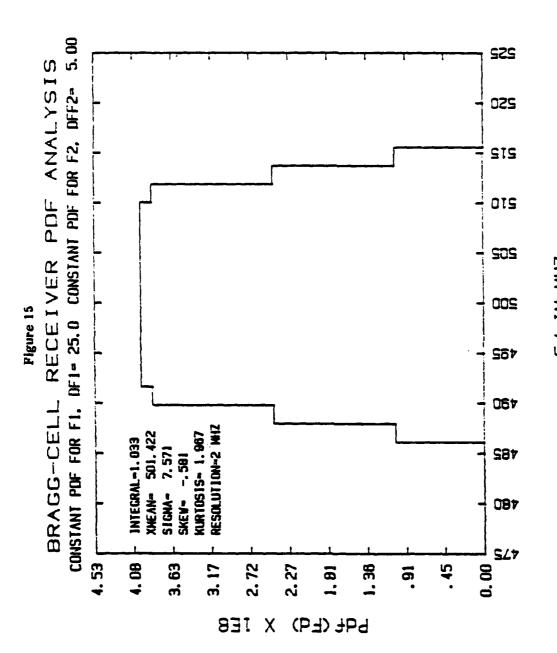
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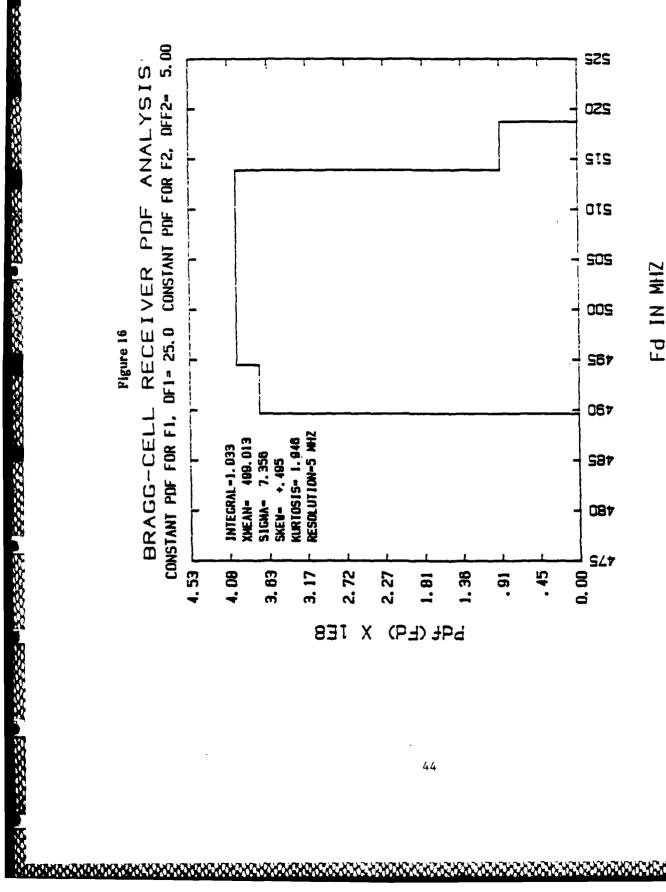
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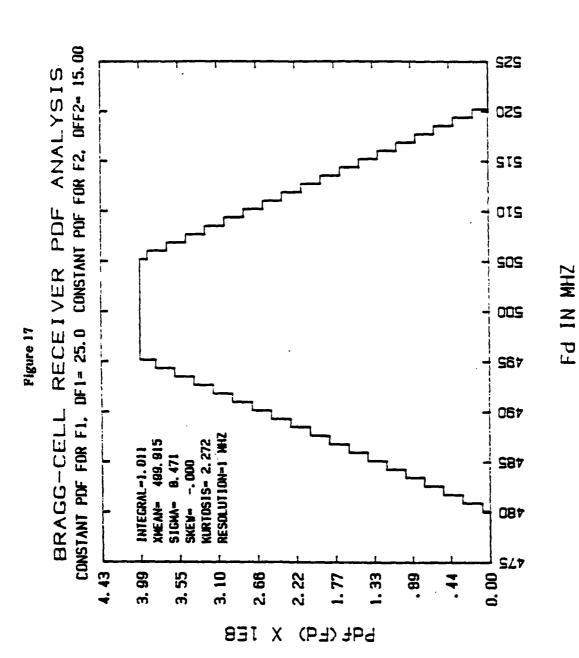
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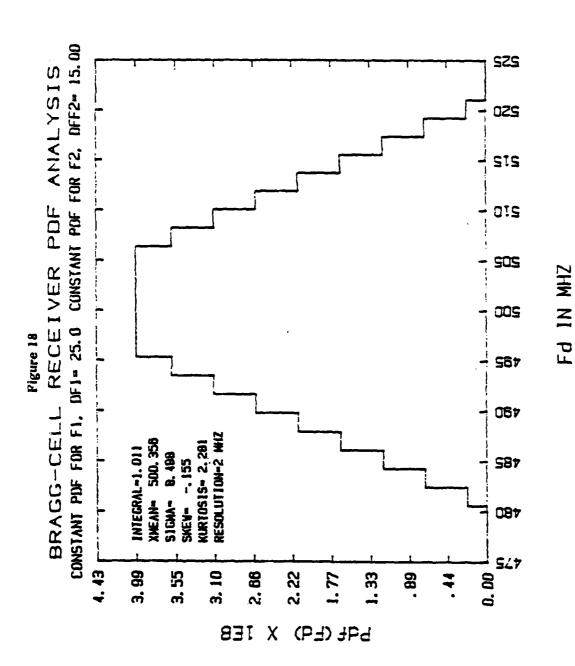
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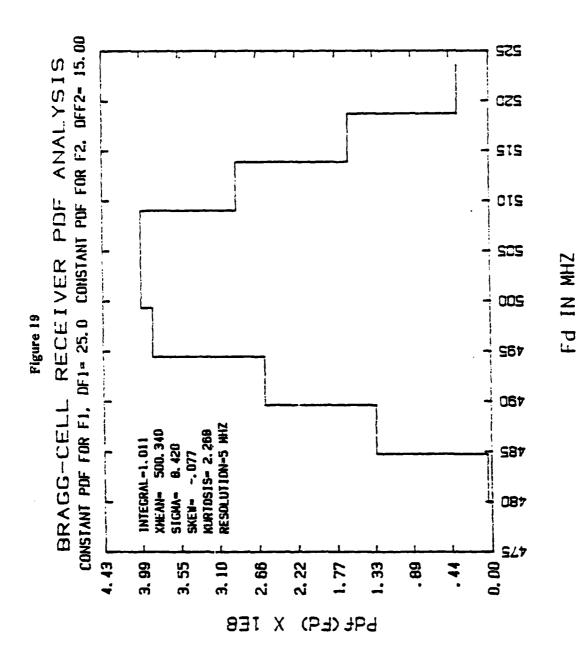
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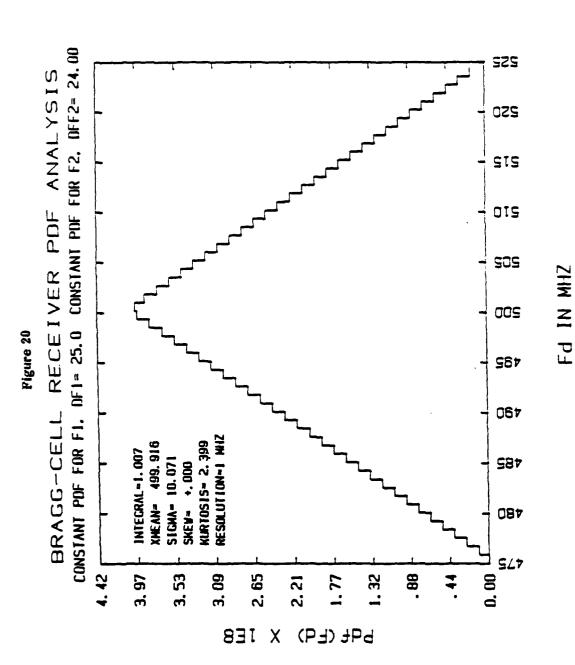
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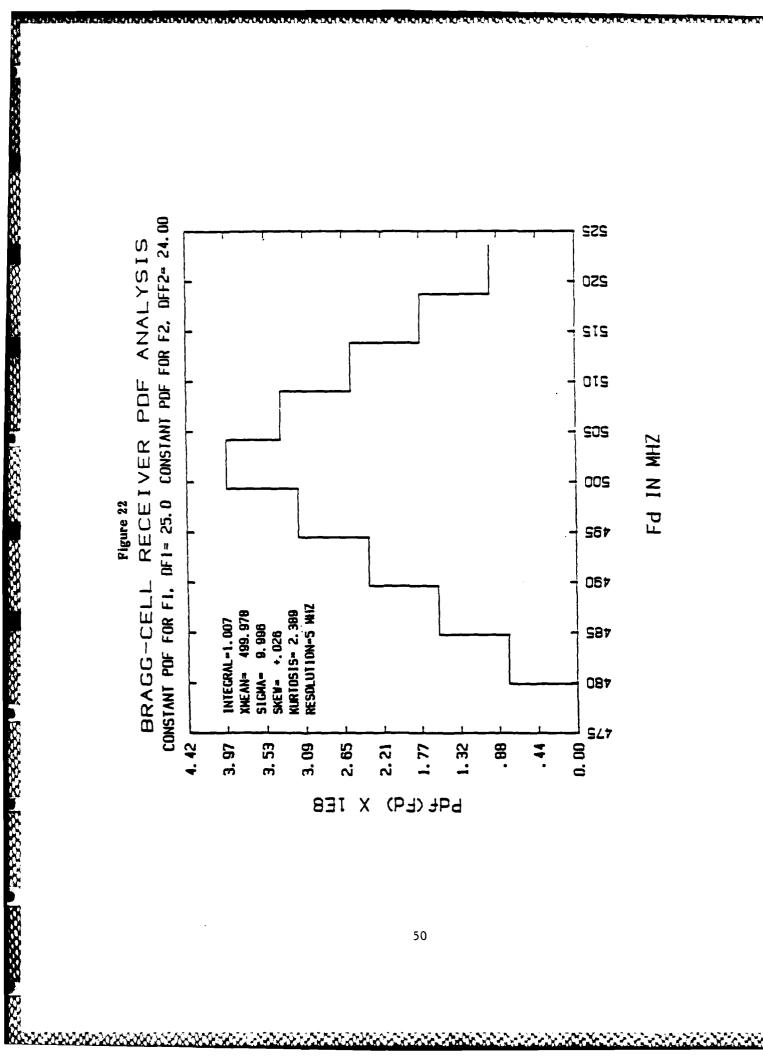
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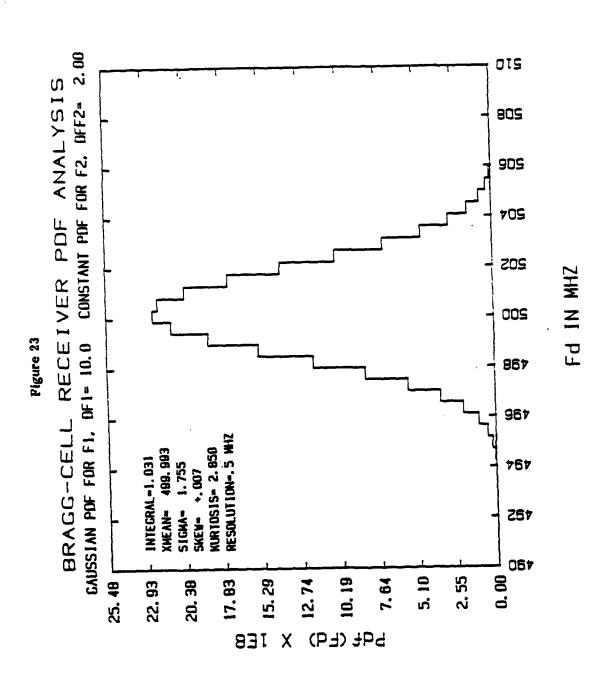
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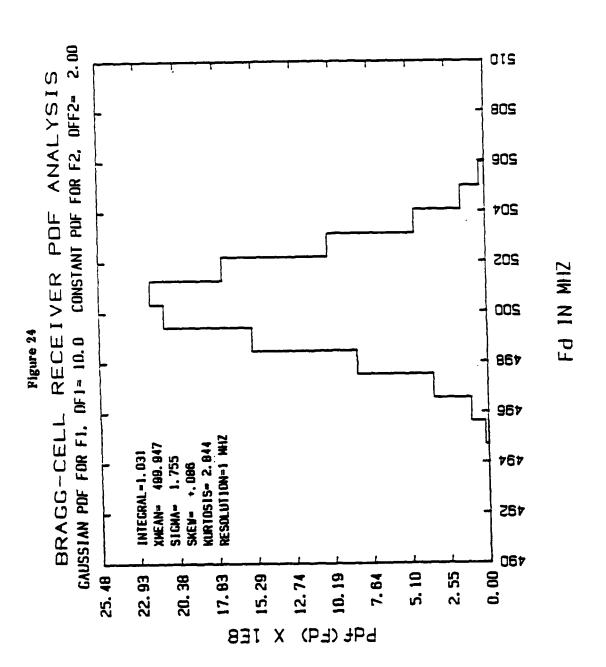
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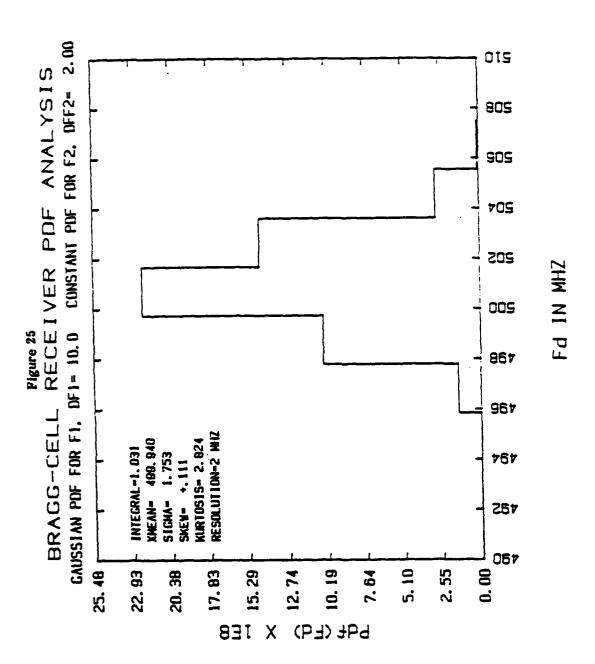
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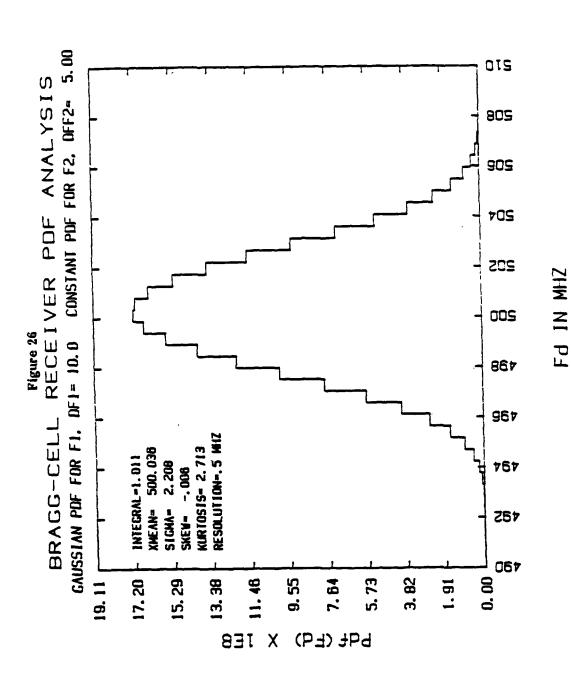
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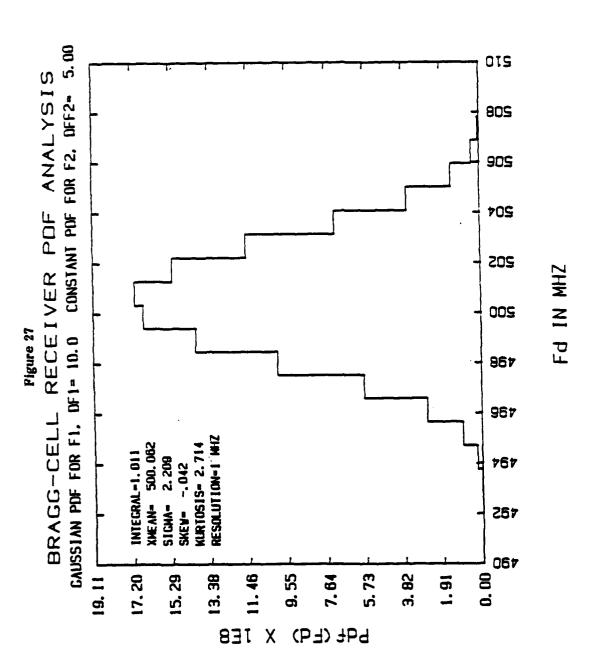


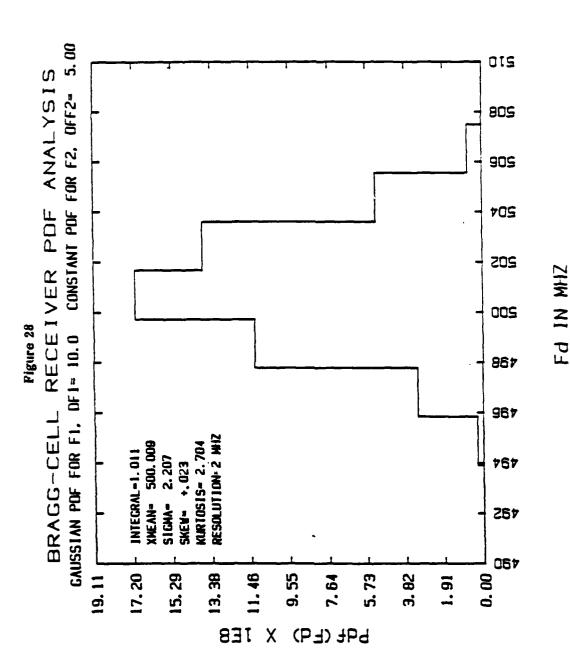
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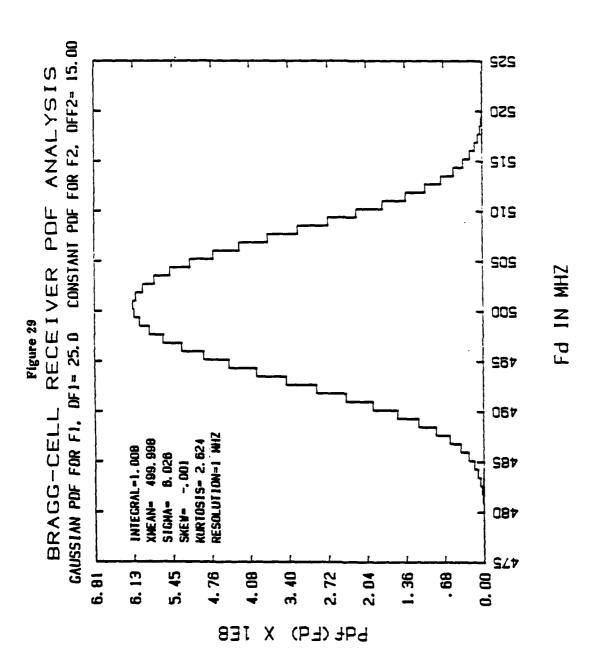
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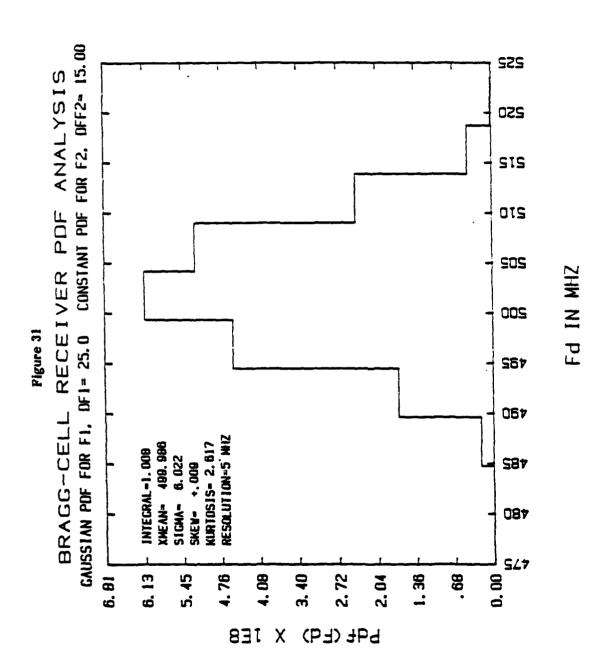
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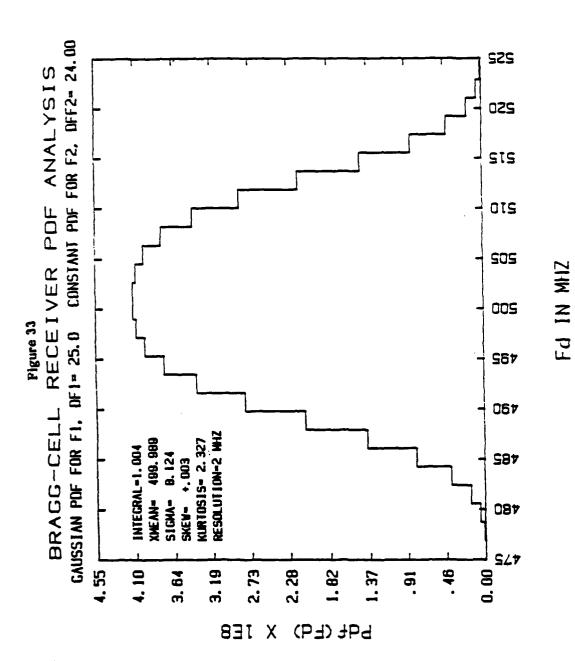
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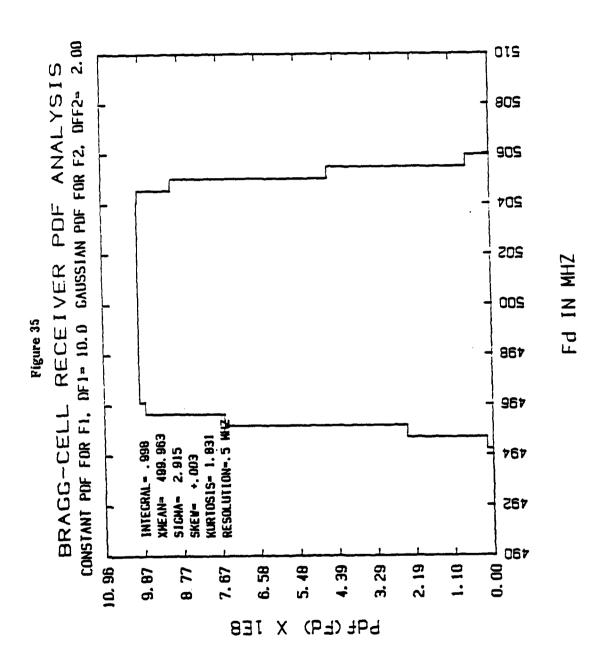
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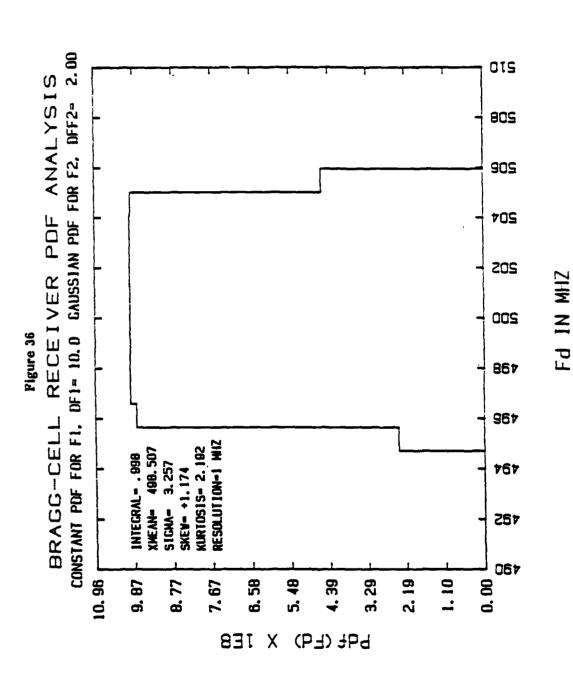
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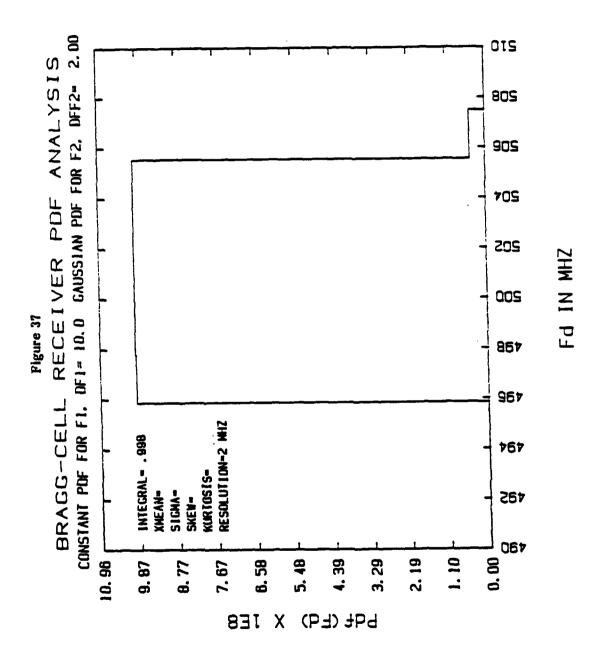
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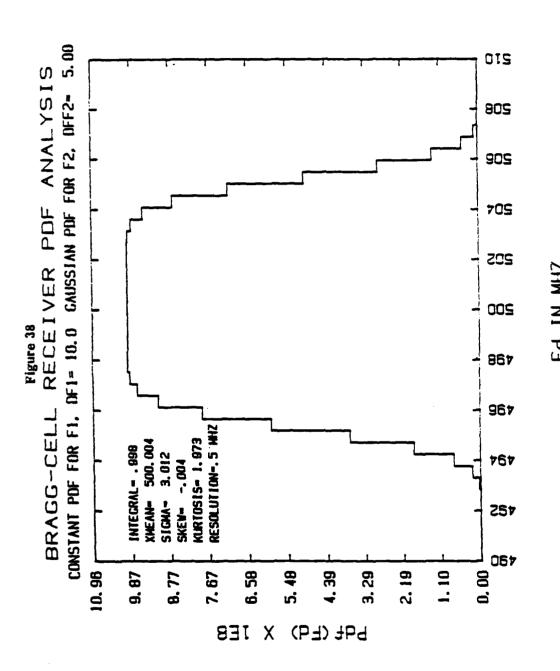
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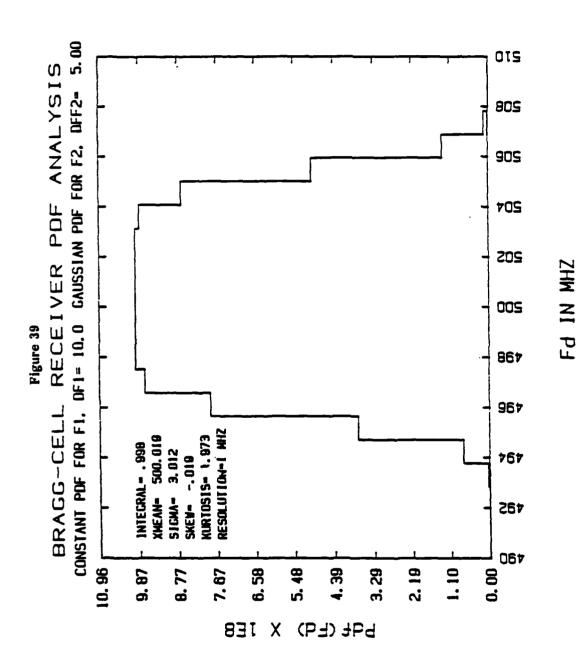
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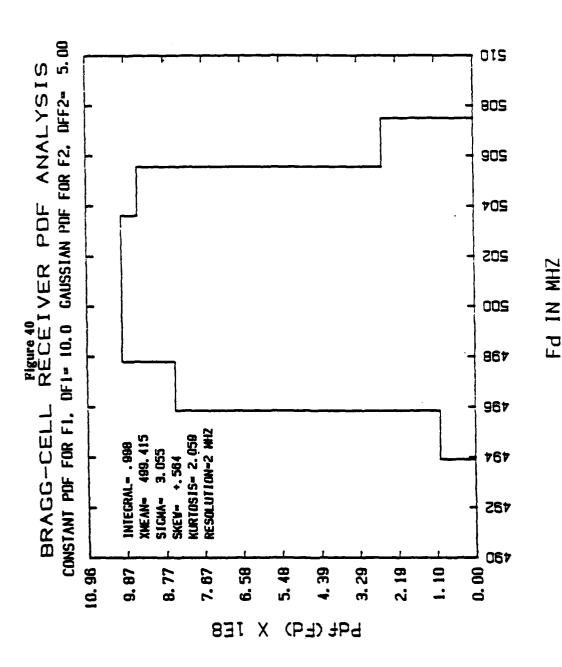




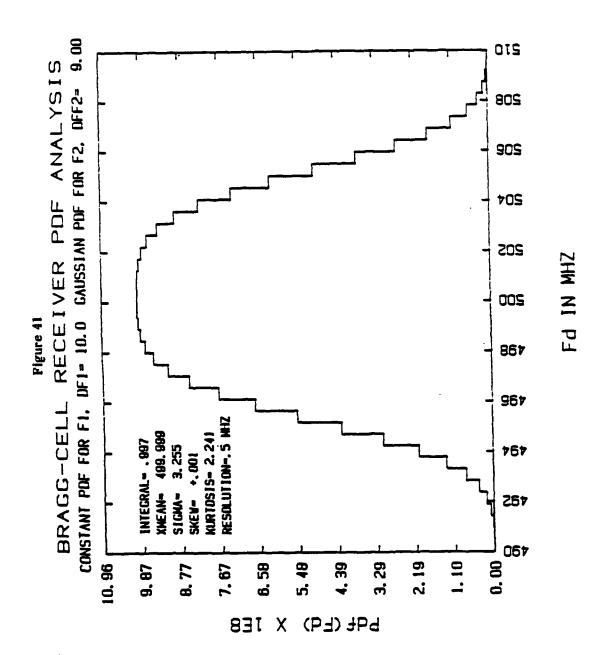
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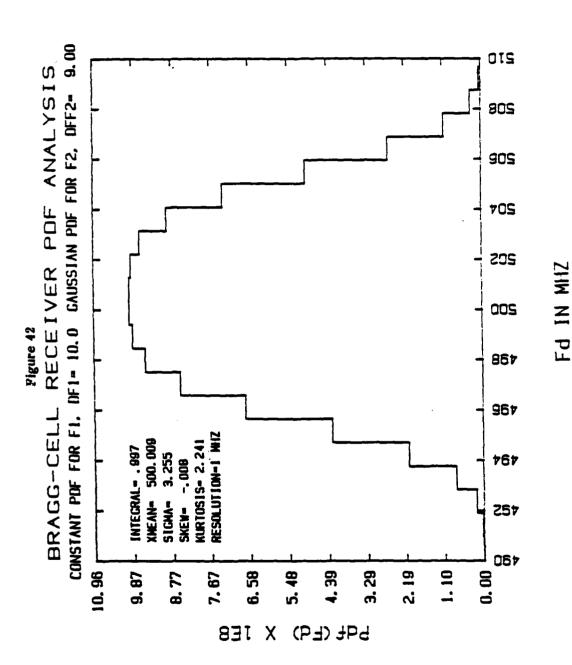


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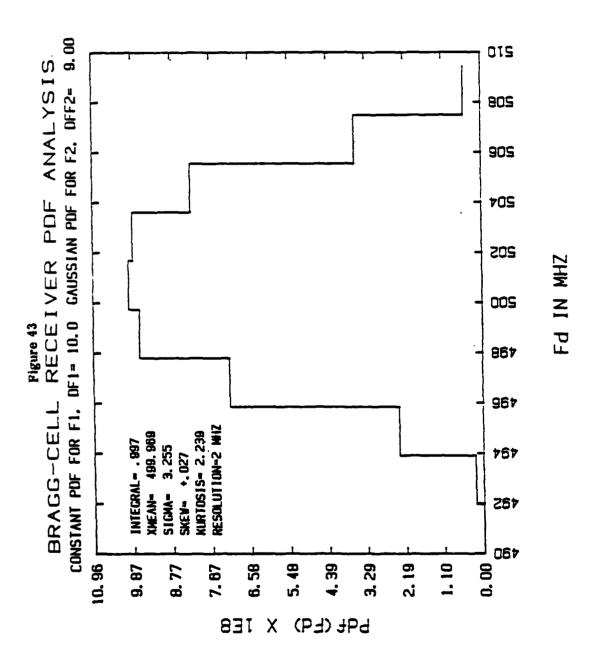
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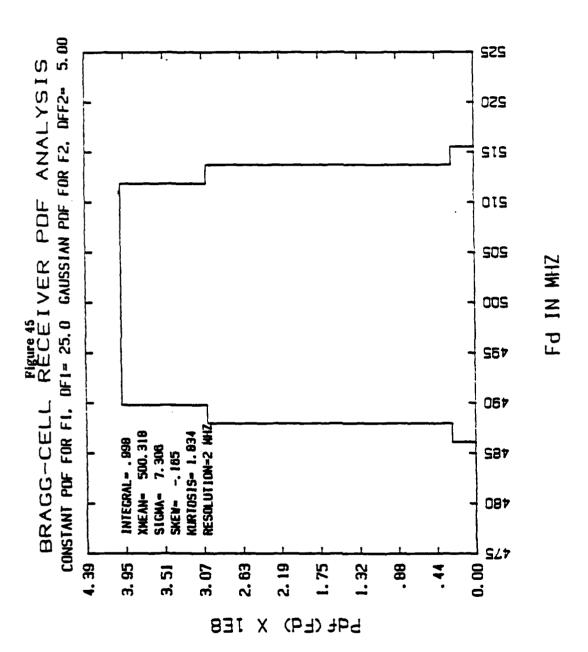
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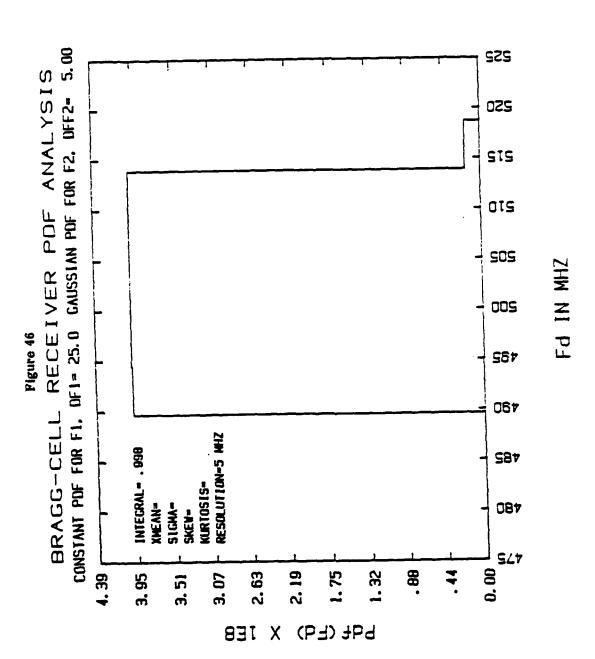
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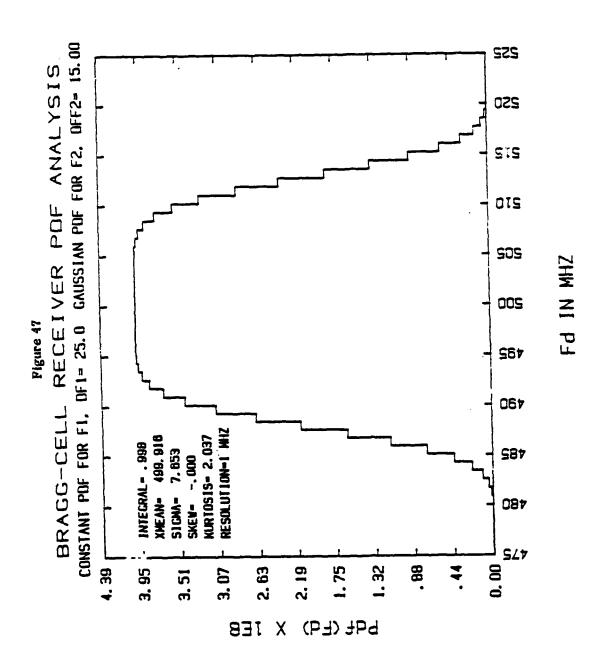
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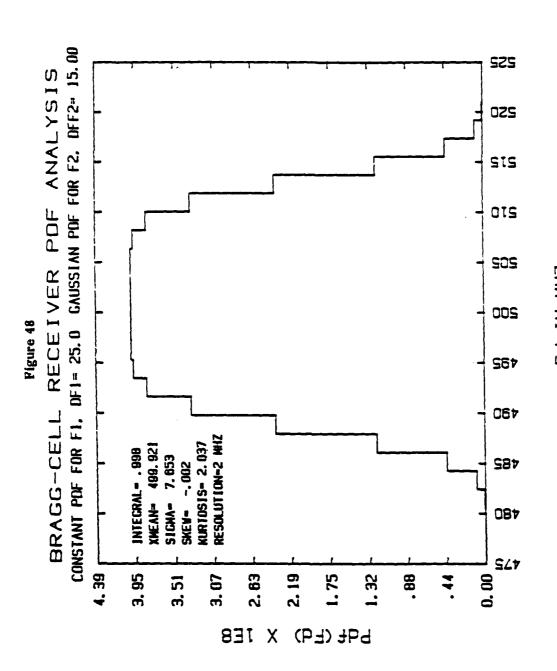
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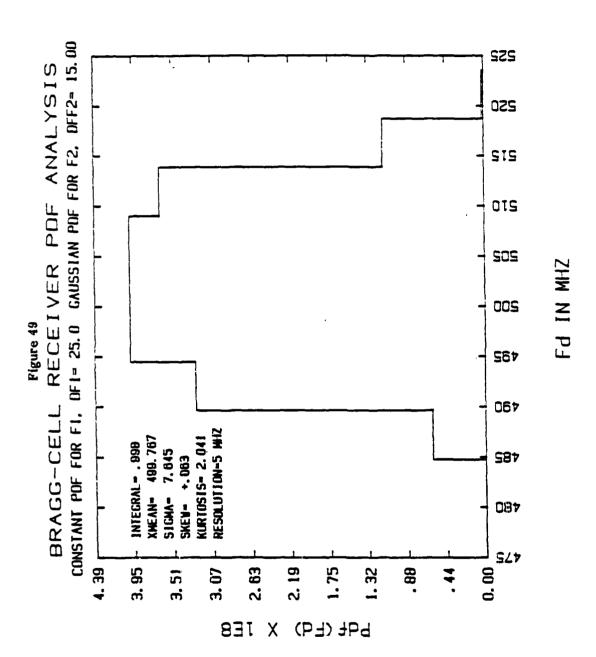


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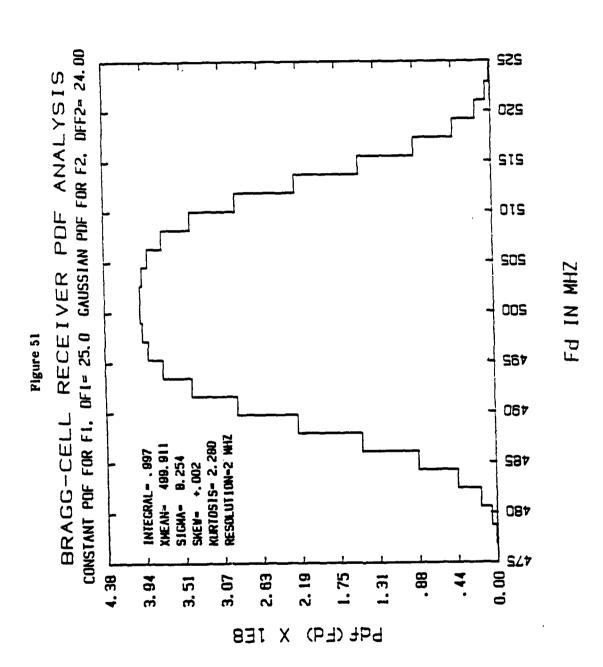
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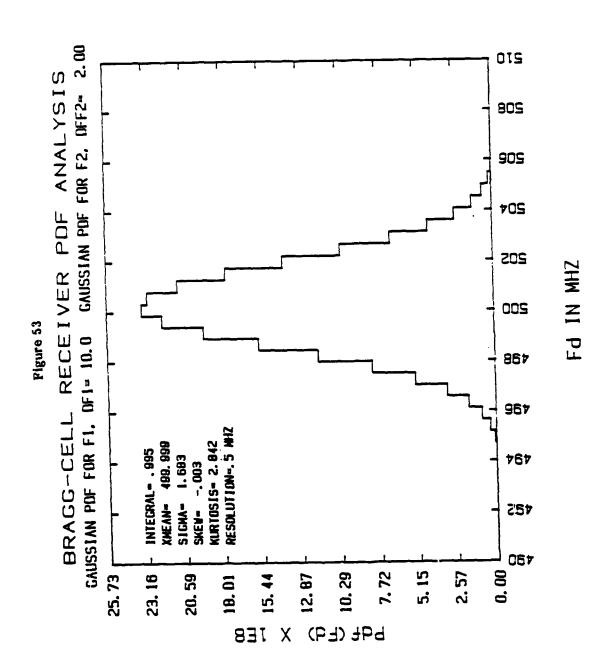
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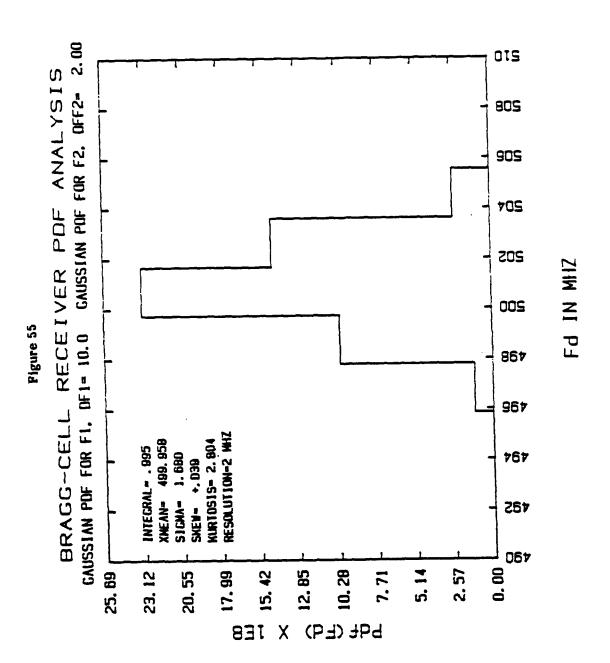
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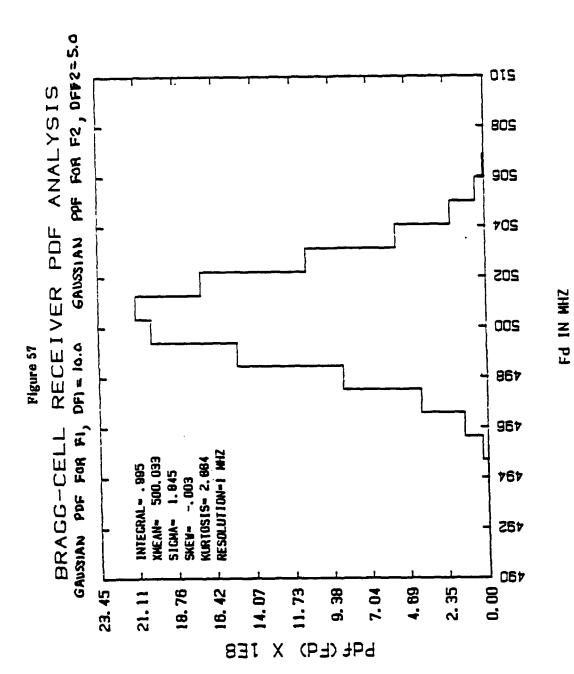
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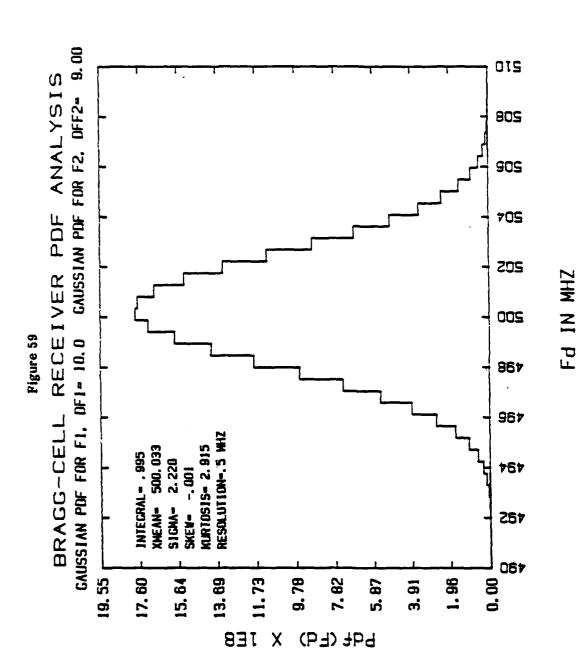
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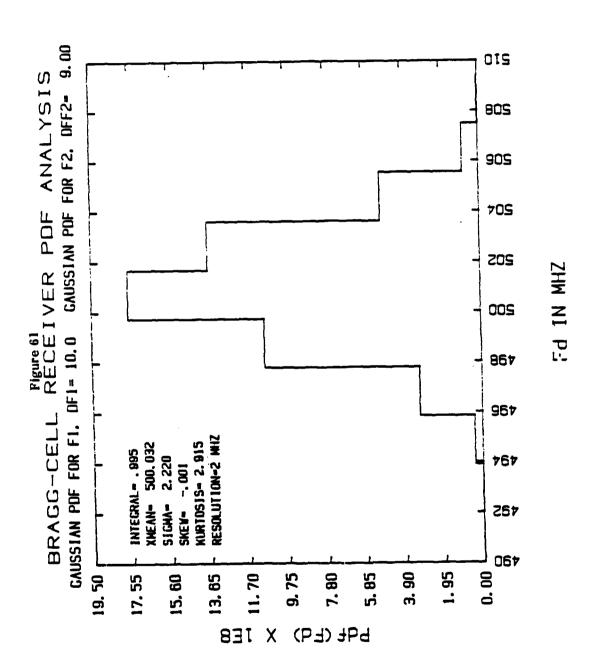
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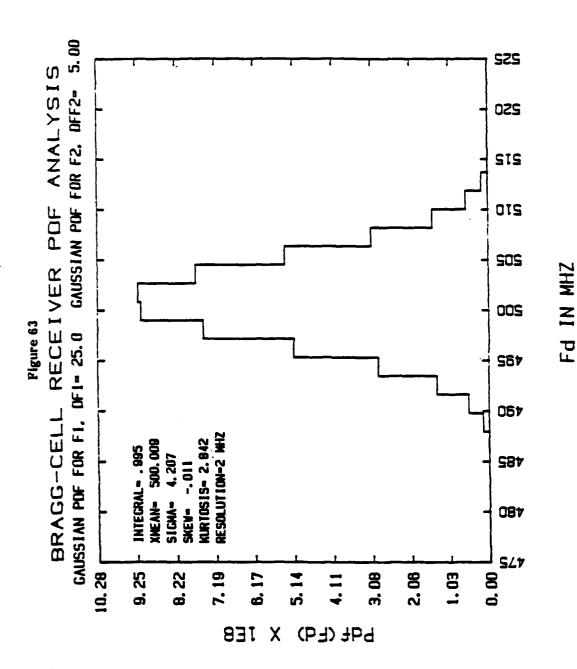
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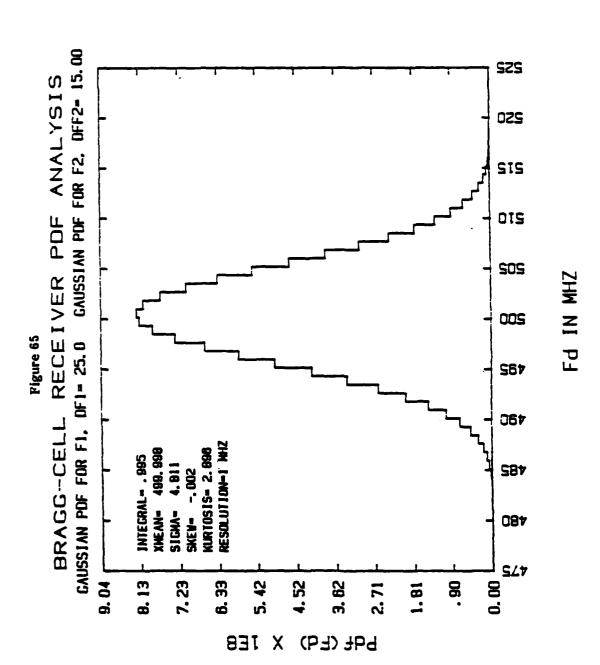
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Figure 64

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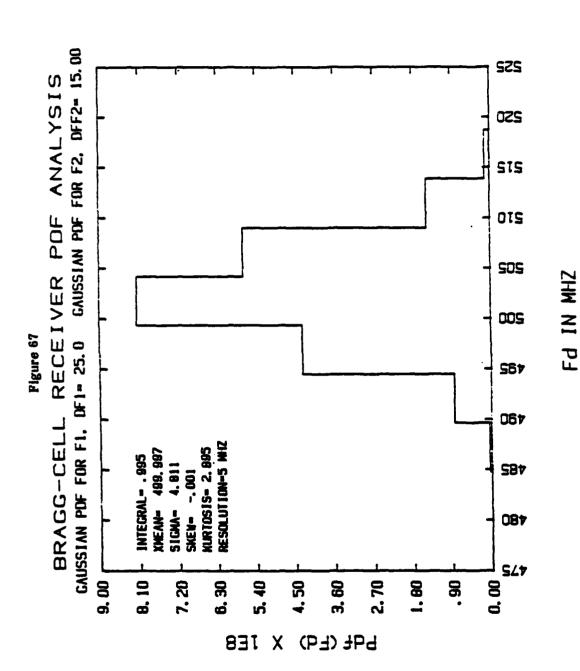
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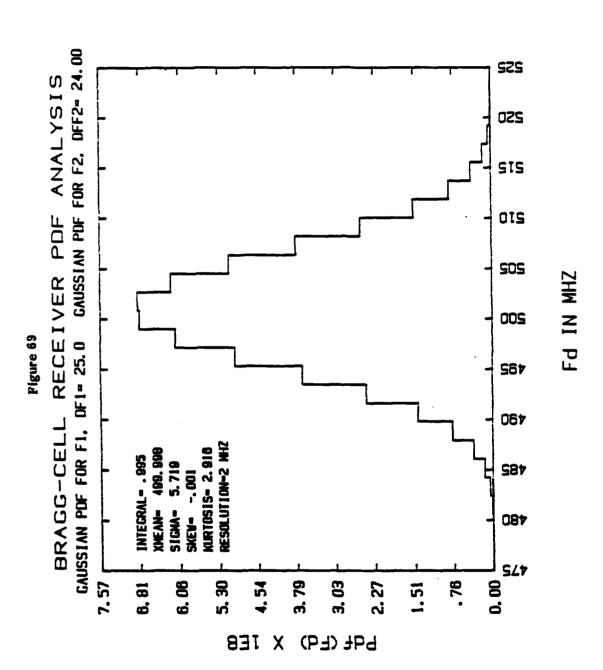
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Figure 68

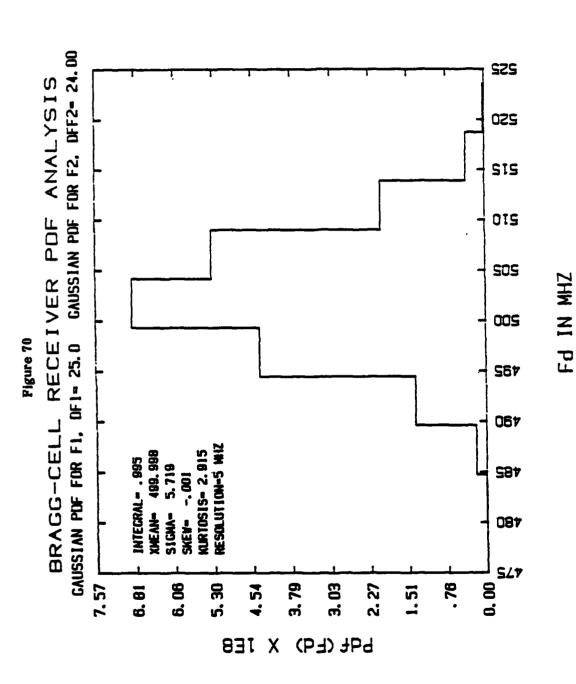
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## CONCLUSIONS

Bragg-cell receivers can accurately measure frequencies of time coincident and time overlapped RF signals, which is a big advantage over other receiver types. Bragg-cell receivers are available with bandwidths to approximately 1 GHz, and frequency resolutions of 100 KHz to 10 MHz.

The Bragg-cell receiver's frequency parameter is analyzed and results are presented in this report. Probability density function analysis and statistical analysis results are presented for this receiver for selected frequency resolution capabilities.

The first order math model is developed for the Bragg-cell receiver. The input signal's frequency is assumed to be a constant pdf or Gaussian pdf characteristic. The primary distortion signal is generated by nonlinear acoustic transducer characteristics. The distortion signal is also assumed to have a constant pdf or Gaussian pdf characteristic.

Staircased pdf characteristics are observed for all pdf frequency characteristics. The staircased function is introduced by the frequency sampling of the photodiode detector array used in the Bragg-cell receiver. The output frequency pdf characteristic is observed to depart from the input signal's frequency pdf characteristic for many of the wideband RF signal cases and wideband distortion signals produced by the AO transducer. Distortion signals with large DF2 values can significantly change the output frequency's pdf characteristic. Also, the frequency sampling (or detector frequency resolution) at the detector can further distort the pdf characteristic. Low frequency resolution at the detector produces the most significant distortions. EW emitter classification and EW direction finding systems can be affected by Bragg-cell receiver distortions. These distortions are especially important for wideband radar emitters.

Math model validation is recommended for the Bragg-cell receiver.

Model validations are readily performed using an actual Bragg-cell receiver and associated test equipment.

## REFERENCES

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- "Microwave Receivers and Related Components," James Tsui, NTIS PB84-108711, 1983.
- 3. "Acousto-Optic Processing Increase EW Capabilities," N. Berg, M. Caseday, and L. Abramovitz. Microwave System News, February 1982.
- 4. "Probability, Random Variable, and Stochastic Processes," A. Papoulis, McGraw-Hill, 1965.

## APPENDIX A BRAGG-CELL RECEIVER CONVOLUTION PROGRAM

```
10 ! "BRAGG" PROGRAM
10 ! BRAGG-CELL RECEIVER ANALYSIS
30 : CONVOLUTION OF FI ARRAY AND FZ ARRAY
40 : THIS VERSION PERMITS STORAGE OF CONVOLVED ARRAY WITH ITS FREQUENCY AXIS
50 : STORAGE TAKES PLACE PRIOR TO PLOTTING--A STRING NAMED INFOS IS ALSO
60 : STORED--SHOULD CONTAIN MINIMUM INFORMATION ON STORED DATA
70 ! PLOT BOTH INPUT ARRAYS ON K AXIS
80 ! PLOT CONVOLUTION ON FREQUENCY AXIS
90 : LABEL TOTAL VALUES FOUND IN CONVOLUTION ARRAY
100 : ARRAYS MAY BE ANY COMBINATION OF FLAT/GAUSSIAN
110 :
           DECEMBER 1986
120 !ISP "DO YOU WANT TO SAVE CONVOLVED ARRAYST" & LINPUT "ENTER Y/N", KP$
130 !IF KPSC1,11="Y" THEN GOSUB KEEP
140 DISP "ENTER INTEGER LENGTH OF LONG ARRAY" & INPUT OF!
150 !DISP "ENTER LENGTH OF SHORT ARRAY" & INPUT DF2
160 DISP "MAKE THESE ENTRIES IN MHZ"
170 DISP "ENTER DELTA FREQUENCY FOR THE LONG ARRAY" @ INPUT DFF1
180 DISP "ENTER DELTA FREQUENCY FOR THE SHORT ARRAY" @ INPUT DFFI
190 OF2=OF1/(DFF1/DFF2) & N=OF1+2 & SGF1=OFF1+10000000/6 & SGFL0=OFF2+10000000/6
200 DISP "DF:=";DF1:" DF2=";DF2:" N=":N @ NMR1=!/(SGF1+SQR(2+PI))
210 OPTION BASE 1 & RAD & NMRLC=1/(SGFLO+SQR(2+PI)) & MU=5000000000
220 DIM PX(500),PH(500),PY(499),TS(82),T1S(52),FX(500),X(500),Y(500),INFQS(80)
230 LIMPUT "ENTER =<80 CHARACTERS DESCRIBING DATA", INFO$
240 REDIM PY(N-1),FX(N-1),PX(N),PH(N)
250 FOR K=1 TO N ! FILL INPUT ARRAYS WITH ZEROES
260 PX(K)=0 & PH(K)=0
270 NEXT K
280 DISP "
                 ----PICK COMBINATION->---
290 DISP "
                 1-BOTH ARRAYS FLAT"
300 DISP "
                 2-SHORT FLAT, LONG GAUSSIAN"
310 DISP "
                 3-LONG FLAT, SHORT GAUSSIAN"
320 DISP "
                 4-BOTH GAUSSIAN"
330 DISP "ENTER YOUR CHOICE" @ INPUT PIC
340 IF PIC=2 THEN SHRT
350 IF PIC=4 THEN GOSUB AR2
360 LSTEP=1
370 FOR K=1 TO N\2 !MAKES FLAT LONG ARRAY
380 PH(K)=1/(DF1-1)
390 NEXT K
400 SHRT:
                    IMAKES FLAT SHORT ARRAY
410 IF PIC=3 THEN GOSUB AR3
420 SSTEP=1
430 FOR K=N/4-CF2/2 TO N/4+CF2/2
 440 PX(K)=1/(DF2-1)
450 NEXT K
460 IF PIC=2 THEN GOSUB AR2
470 CNVLV:
480 YTOT=0
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490 FOR K=1 TO N-1

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500 YSUM=0
SID STL=SOO-OFF: a STPL=SOO+OFF: a STZL=(STPL-STL)/(N-1) a IVAL=STL+STZL/Z
520 FOR J=1 TO K
SEO YSUM=YSUM+PX(J)+PH(K-J+1)
540 PY(K)=YSUM/(STZL+10000000)
SSO NEXT J
550 IF K MOD 50=0 THEN DISP "K=";K
570 NEXT K
580 FOR K=1 TO N-1 ! MAKE FREQ ARRAY FOR XAXIS
590 FX(K)=IVAL
500 IVAL=IVAL+STZL.
610 NEXT K
620 SUMY=0
630 FOR K=1 TO N-2 !INTEGRATE
640 XS=(FX(K+1)-FX(K))+1000000
650 YS=(PY(K)+PY(K+1))/2
660 SUMY=XS+YS+SUMY
670 NEXT K
680 DISP "SUM="; SUMY
690 !IF KPS(1,11="Y" THEN GOSUB KP1
                       PICK PLOT
700 CHOICE: !
                  1-PLOT BOTH ORIGINAL ARRAYS SAME AXIS"
710 DISP "
                 Z-PLOT CONVOLUTION ON FREQUENCY AXIS"
720 DISP "
730 DISP "
                 3-EXIT PROGRAM"
                 4-STORE DATA"
740 DISP
                 ENTER YOUR CHOICE" @ INPUT CH
750 DISP "
760 IF CH=4 THEN GOSUB KEEP
 770 IF CH#1 THEN 790
 780 LINPUT "EXTERNAL PLOTTER? Y/N", HPS
 790 IF CH=3 THEN BEEP & DISP "DONE" & STOP
 800 IF CH=1 THEN GOSUB PLT1
 810 IF CH=2 THEN GOSUB PLT3
 820 PLOTTER IS 1 @ PEN -1 @ GCLEAR @ LOCATE 30,170,25.80
 830 Y1=0 & Y2=AMAX(Y)+1.1 & X1=STL & X2=STPL
 840 START:
 850 SCALE X1,X2,Y1,Y2
 860 FXD Z @ LAXES (X2-X1)/10,(YZ-Y1)/10,X1,Y1
 870 XAXIS YZ,(X2-X1)/10,X1,XZ
 880 YAXIS XZ,(Y2-Y1)/10,Y1,Y2
                                 ADD MORE DATA SAME SCALE
 890 MORCAT: !
 900 IF CH=1 THEN 950
 910 IF CH=4 THEN 950
 920 DISP "ENTER BRAGG-RECEIVER FREQUENCY RESOLUTION"
 930 INPUT RES
 940 KRES-INT(RES/(Z+OFF1/N))
 950 FOR K=1 TC TOP
 960 PLOT X(K),Y(K) & IF CH-1 THEN 1040
 970 IF CH=4 THEN 1040
 980 FOR L=1 TO KRES
 990 IF K+L>=TOP THEN 1050
  1000 PLOT X(K+L),Y(K)
  1010 NEXT L
  1020 K=K+L-2
  1030 L=1
  1040 NEXT K
  1050 IF HPS="Y" THEN EPLOT
  1060 IF CH=1 THEN GOSUB PLTZ
  1070 IF CH=4 THEN PLOUT
                                       103
```

```
1080 IMAGE "CONSTANT POF FOR F1, OF1=",OD.O." CONSTANT POF FOR F2 , OFF2=",OD.O.
1090 IMAGE "CONSTANT POF FOR F1, OF1=",CD.D," GAUSSIAN POF FOR FZ , OFFZ=",CD.D
1100 IMAGE "GAUSSIAN POF FOR F1. OF1=".DD.D." CONSTANT POF FOR F2 . DFF2=".DD.
0."
1110 IMAGE "GAUSSIAN POF FOR F1, CF1=",CD.D." GAUSSIAN POF FOR FZ , OFFZ=",DD.
0,"
1:20 Ta="GRAGG-CELL RECEIVER POF ANALYSIS" & CSIZE 3.3.1
1130 LORG 5 @ MOVE X2-(X2-X1)/2,Y2+(Y2-Y1)/9 @ LABEL USING "K" ; T$
1140 CSIZE 3
1150 MOVE X2-(X2-X1)/2,Y2+(Y2-Y1)/18 & IF PIC=1 THEN LABEL USING :080 : OFF1.DFF
2 @ CSIZE 3
1160 IF PIC=3 THEN LABEL USING 1090 ; OFF1, OFF2 & CSIZE 4
1170 IF PIC=2 THEN LABEL USING 1100 : DEF1.DEF2 @
1180 IF PIC-4 THEN LABEL USING 1110 : OFF1 OFF2 & CSIZE 4
1190 MOVE X2-(X2-X1)/2.Y1-(Y2-Y1)/5 & LABEL USING "K" ; "FD IN MHZ"
1200 MOVE X1-(X2-X1)/7, Y2-(Y2-Y1)/2 & DEG & LDIR 30 & LABEL USING "K" ; "Pdf(FD)
X 158"
1210 IMAGE "TOTAL=",DD.DDD
1220 MOVE X1, Y1-(Y2-Y1)/5 & LDIR 0 & LORG 2 & LABEL USING 1210 : SUMY
1230 PLGUT:
1240 LINPUT "DUMP GRAPHICS? Y/N".DG&
1250 IF DG = "Y" THEN DUMP GRAPHICS
1250 EPLOT:
1270 HPs="N"
1280 LINPUT "PLOT ON EXTERNAL DEVICE? Y/N" PLES
1290 IF PLES="Y" THEN PLOTTER IS 705 @ PEN 1 @ LOCATE 30,110,29,89 @ GOTO START
1300 IF CH=4 OR CH=2 THEN CHOICE
1310 BEEP 150.300 @ DISP "DONE"
1320 END
1330 PLT1: 1
                       PLOT SHORT ARRAY
1340 REDIM X(N),Y(N)
1350 IF CH=1 THEN MULT=1 ELSE MULT=100000000
1360 FOR K=1 TO N IFILL X AND Y ARRAYS
1370 X(K)=K & Y(K)=PX(K)+MULT
1380 NEXT K
1390 X1=1 & X2=N & Y1=0 & Y2=AMAX(Y)+1.1 & TOP=N & LINE TYPE 1
1400 PLOTTER IS 1 @ PEN -1 @ GCLEAR @ LOCATE 30.170.25.80
1410 GOTO START
1420 RETURN
1430 PLTZ: 1
                        PLOT LONG ARRAY SAME SCALE
1440 TS="INPUT ARRAYS"
1450 IMAGE "CONSTANT ARRAY FOR F1, DF1=",DD.D." CONSTANT ARRAY FOR F2 . DFFZ=".
1460 IMAGE "CONSTANT ARRAY FOR F1, DF1=",DD.D." GAUSSIAN ARRAY FOR F2 . DFF2=".
1470 IMAGE "GAUSSIAN ARRAY FOR FI, DFI=",DD.D," CONSTANT ARRAY FOR F2 , DFFZ=",
1480 IMAGE "GAUSSIAN ARRAY FOR F! DF!=".DD.D." GAUSSIAN ARRAY FOR FZ . DFF2=".
00.00
1490 LORG 5
1500 MOVE X2-(X2-X1)/2, Y2+(Y2-Y1)/20 & IF PIC=2 THEN LABEL USING 1470 ; DFF: DFF
1510 MOVE XZ-(XZ-X1)/2, YZ+(YZ-Y1)/20 8 IF PIC=1 THEN LABEL USING 1450 ; OFF1, DFF
1520 MOVE X2-(X2-X1)/2, Y2+(Y2-Y1)/20 @ IF PIC=3 THEN LABEL USING 1460 ; OFF1, DFF
Z & CSIZE 4
                                     104
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1530 MOVE XZ-(XZ-X1)/2,YZ+(YZ-Y1)/20 & IF PIC=4 THEN LABEL USING 1480 ; DFF1.DFF
Z & CSIZE 4
1540 LORG 5 9 MOVE X2-(X2-X1)/2.Y2+(Y2-Y1)/9 8 LABEL USING "X" ; T$
1550 IF CH=1 THEN MULT=1 ELSE MULT=1000000000
1550 MOVE X1-(XZ-X1)/7.Y2-(YZ-Y1)/Z @ DEG @ LDIR 90 @ LABEL USING "K" ; "VALUE X
 "; MULT
1570 FOR K=1 TO N
1580 Y(K)=PH(K)+MULT
1530 NEXT K
1600 CH=4 & LINE TYPE 4 & TOP=N
1610 GOTO MORDAT
1620 RETURN
1630 PLT3: 1
                        FILL CONVOLUTION ARRAY
1640 REDIM X(N-1), Y(N-1)
1650 MULT=1000000000
1650 FOR K=1 TO N-1
1670 X(K)=FX(K) @ Y(K)=PY(K)+MULT
1680 NEXT K
1630 TOP=N-1
1700 RETURN
             !SUB-GENERATE GAUSSIAN FOR THE LONG ARRAY
1710 AR2:
1720 Stt=MU-3+SGF1 @ Stp=MU+3+SGF1 @ STZ=(Stp-Stt)/(N\2) @ IVL=Stt
1730 FOR K=1 TO N\2
1740 PH(K)=NMR1+EXP((-(IVL-MU)*2)/(Z+SGF1*2)) @ PH(K)=PH(K)+STZ
1750 IVL=IVL+STZ
1760 NEXT K
1770 IF PIC=4 THEN AR3
1780 IF PIC=2 THEN CNVLV
1790 RETURN
              ! SUB-GENERATE GAUSSIAN FOR THE SHORT ARRAY
1800 AR3:
1810 Stt=MU-3+SGFLO @ Stp=MU+3+SGFLO @ STZ=(Stp-Stt)/(N/4+DFZ/Z-(N/4-DFZ/Z)) @ I
VL=Stt
1820 FOR K=N/4-DFZ/2 TO N/4+DFZ/2
1830 PX(K)=NMRL0+EXP((-(IVL-MU)^2)/(2+SGFL0*2)) @ PX(K)=PX(K)+ST2
1840 IVL=IVL+STZ
1850 NEXT K
1860 IF PIC=3 OR PIC=4 THEN CNVLV
1870 RETURN
1880 KEEP: |
                         FILENAME ENTRY
 1890 DISP "FILENAME MUST BE ENTERED IN UNIX PATH FORM /DISCNAME/FILENAME"
1900 LINPUT "ENTER DESCRIPTIVE FILENAME".FS
1910 CREATE FS.1.299+2+89
 1920 ASSIGN# 1 TO F#
 1930 PRINT# 1 ; N.INFOS.FX(),PY()
 1940 ASSIGN# 1 TO .
 1950 GOTO CHOICE
 1960 RETURN
```

## APPENDIX A BRAGG-CELL RECEIVER PDF GENERATION & STATISTICAL ANALYSIS PROGRAM

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```
THIS PROGRAM COMPUTES BRAGG-CELL ROVE, POF AND STATISTICS
             THIS PROGRAM GETS DATA FROM A CONVOLVOLUTION FILE-DOES CEN MOMS
: 20 :
20 :DATA IS THEN PLOTTED WITH LABELLED CENTRAL MOMENTS, INT. ETC....
ID OPTION BASE :
40 OIM FX(500), PH(500), INFOS(80), TS(75)
50 DISP "PLEASE USE FILENAMES WITH 2 DIGITS FOR DELT
60 LINPUT "FILENAME?" F8
70 ASSIGN# : TO F#
80 READ# 1 : N 9 N=N-1
(N)PS, (N)XS MICES 08
100 REAC# : : INFOS,FX().PH()
110 FOR K=1 TO N
120 FX(K)=FX(K)+100
130 NEXT K
140 ASSISN# : TO +
150 DISP 0 DISP INFOS 9 DISP
160 F:s=REVS(FS) 9 PS=F18[1.1]
170 IF PS='A" THEN PIC=!
180 IF PS=18" THEN PIC=2
190 IF PS="0" THEN PIC=3
200 IF PS="0" THEN PIC=4
210 OF1=VAL(F3(3,41) 0 OFLO=VAL(F3(8,71)
220 DISP "ENTER RESOLUTION IN MHZ" @ INPUT RES
230 XST=INT(RES/(2-0F1/N))
240 OFM=AMAX(FX)-AMIN(FX) @ FSTPM=OFM/(N-1)-XST @ OF=FSTPM-10000000.0 SUMZ=0
250 SUMY=0 3 SUMS=0 3 SUM3=0 3 SUM4=0
250 FOR K=1 TO N-1
270 XS=(FX(K+1)-FX(K))+1000000 0 YS=(PH(K)+PH(K+1))/2
280 SUMZ=SUMZ+XS+YS
290 NEXT K
300 FOR K=1 TO N STEP XST
310 FX(K)=FX(K)+1000000
320 PH(K)=PH(K)/SUMZ
330 SUMY=SUMY+PH(K)+FX(K)+OF
340 NEXT K
350 XMEAN=SUMY
360 FOR K=1 TO N STEP XST
370 SUMS=SUMS+(FX(K)-XMEAN)^2+PH(K)+OF
380 NEXT K
390 UNC=SUMS & SIGMA=SCR(UNC)
 400 FOR K=1 TO N STEP XST
410 SUM3=SUM3+(FX(K)-XMEAN)"3+PH(K)+OF
 420 SUM4=SUM4+(FX(K)-XMEAN)^4+PH(K)+DF
 430 NEXT K
 440 CM3=SUM3 0 CM4=SUM4
 450 SKEW=CH3/VNC~1.5 @ KURT=CM4/VNC~2
 460 PLOTTER IS 1 @ PEN -1 @ GCLEAR @ LOCATE 30,170,25,80
 470 Y1=0 0 Y2=AMAX(PH)+1000000000+1.1 0 X1=FX(1)/1000000 0 X2=X5+N/1000000/2+500
 480 START:
```

```
490 SCALE X1,X2,Y1,Y2
500 FXD 0.2 0 LAXES (X2-X1)/10,(Y2-Y1)/10,X1,Y1
SX, 1X, 61/(1)-5X), SY SIXAX 612
529 YAXIS X2,(Y2-/1)/10,Y1,Y2
530 MORDAT: 1
                                ADD MORE DATA SAME SCALE
540 FOR K=! TO N STEP XST
SEO IF K+XSTON THEN SEO
SEO PLOT FX(K)/1000000,PH(K)+1000000000 $ PLOT FX(K+XST)/10000000,PH(K)+1000000000
570 NEXT K
ESO IMAGE "CONSTANT POF FOR F1, DF1=",DDD.D," CONSTANT PDF FOR F2, DFF2=",DDD.D
530 IMAGE "CONSTANT FOR FOR FI, DF1=",DDD.D," GAUSSIAN POF FOR F2, DFF2=",DDD.D
800 IMAGE "GAUSSIAN POF FOR F1, OF1=", DDD.D,"
                                                CONSTANT POF FOR FZ, OFFZ=".DDD.
6:0 IMAGE "SAUSSIAN POF FOR F1, DF1=",000.0." GAUSSIAN POF FOR F2, DFF2=",000.
30
529 Ts="3RAGG-CELL RECEIVER POF ANALYSIS" @ CSIZE 3.3.1
630 LORG 5 0 MOVE X2-(X2-X1)/2,Y2+(Y2-Y1)/9 0 LABEL USING "K" ; T3
440 CSIZE 3
650 MOVE X2-(X2-X1)/2,Y2+(Y2-Y1)/18 8 IF PIC=1 THEN LABEL USING 580 : OF1,DFLO a
- CSIZE 4
$60 IF PIC=3 THEN LABEL USING $30 : DF1,DFL0 @ CSIZE 4
570 IF PIC=2 THEN LABEL USING 500 : OF1.0FLO & CSIZE 4
630 IF PIC=4 THEN LABEL USING 610 : OF1, DFLO 9 CSIZE 4
690 MOVE X2-(X2-X1)/2,Y1-(Y2-Y1)/5 @ LORG 5 @ LABEL USING "K" : "Fd IN MHZ"
700 LORG 5 8 CSIZE 4 8 LORG 5
710 MOVE X1-(X2-X1)/7, Y2-(Y2-Y1)/2 0 DEG 0 LDIR 90 0 LABEL USING "K"; "Pdf(Fd)
X 1E3.
720 LDIR 0 8 RAC
730 IMAGE "INTEGRAL=",0.000
740 IMAGE "XMEAN=",00000.000
750 IMAGE "SIGMA=" DCD.DDD
780 IMAGE "SKEW=",500.000
770 IMAGE "KURTOSIS=",DD.DDD
780 CSIZE 2.5 2 LORG 2
790 MOVE X1+(X2-X1)/25,Y2-(Y2-Y1)/10 0 LABEL USING 730 ; SUMZ
800 LABEL USING 740 : XMEAN/1000000
810 LABEL USING 750 ; SIGMA/1000000
820 LABEL USING 760 1 SKEW
830 LABEL USING 770 : KURT
840 LABEL USING "K" ; "RESOLUTION="; RES; MHZ"
850 LINPUT "DUMP GRAPHICS? Y/N" .6DMs
860 IF GOMS[1,1]="Y" THEN DUMP GRAPHICS
870 IF EPLS="Y" THEN 900
880 LINPUT "PLOT ON EXTERNAL DEVICE? Y/N" .EPLS
890 IF EPLS="Y" THEN PLOTTER IS 705 0 PEN 1 0 LOCATE 30,110,29,89 0 GOTO START
900 SEEP 300,400 9 DISP "CONE"
 910 END
```